

# Discrete Schwarz Methods: Discretizations of Continuous Schwarz Methods ?

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Classical Schwarz

Continuous  
Discrete

Problems of  
Classical Schwarz

Overlap Required  
No Convergence  
Convergence Speed

Optimized Schwarz

Continuous  
Discrete

Applications

Airplane, Climate  
Twingo

Conclusions

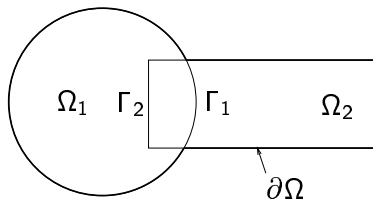
# Classical Alternating Schwarz Method



H. A. Schwarz 1869:

“Nachdem gezeigt ist, dass für eine Anzahl von einfacheren Bereichen die Differentialgleichung  $\Delta u = 0$  beliebigen Grenzbedingungen gemäss integriert werden kann, handelt es sich darum, den Nachweis zu führen, dass auch für einen weniger einfachen Bereich, der aus jenen auf gewisse Weise zusammengesetzt ist, die Integration der Differentialgleichung beliebigen Grenzbedingungen gemäss möglich ist”.

$$\mathcal{L}u = f \text{ in } \Omega$$



$$\begin{aligned}\mathcal{L}u_1^{n+1} &= f, \text{ in } \Omega_1 \\ u_1^{n+1} &= u_2^n, \text{ on } \Gamma_1\end{aligned}$$

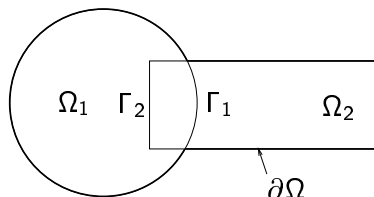
$$\begin{aligned}\mathcal{L}u_2^{n+1} &= f, \text{ in } \Omega_2 \\ u_2^{n+1} &= u_1^{n+1}, \text{ on } \Gamma_2\end{aligned}$$

# Classical Parallel Schwarz Method

P-L. Lions 1988:

*The final extension we wish to consider concerns “parallel” versions of the Schwarz alternating method*  
 $\dots, \dots, u_i^{n+1}$  is solution of  $-\Delta u_i^{n+1} = f$  in  $\Omega_i$  and  $u_i^{n+1} = u_j^n$  on  $\partial\Omega_i \cap \Omega_j$ .

$$\mathcal{L}u = f \text{ in } \Omega$$



$$\begin{aligned}\mathcal{L}u_1^{n+1} &= f, \text{ in } \Omega_1 \\ u_1^{n+1} &= u_2^n, \text{ on } \Gamma_1\end{aligned}$$

$$\begin{aligned}\mathcal{L}u_2^{n+1} &= f, \text{ in } \Omega_2 \\ u_2^{n+1} &= u_1^n, \text{ on } \Gamma_2\end{aligned}$$

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## Relation with Alternating Schwarz

If the  $R_j$  are non-overlapping, and we partition accordingly

$$A = \begin{bmatrix} A_1 & A_{12} \\ A_{21} & A_2 \end{bmatrix}, \quad \mathbf{f} = \begin{pmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \end{pmatrix},$$

we obtain from the first relation of MS, i.e.

$$\mathbf{u}^{n+\frac{1}{2}} = \mathbf{u}^n + R_1^T A_1^{-1} R_1 (\mathbf{f} - A \mathbf{u}^n)$$

an interesting cancellation:

$$\begin{aligned} R_1(\mathbf{f} - A \mathbf{u}^n) &= \mathbf{f}_1 - A_1 \mathbf{u}_1^n - A_{12} \mathbf{u}_2^n \\ A_1^{-1} R_1(\mathbf{f} - A \mathbf{u}^n) &= A_1^{-1}(\mathbf{f}_1 - A_{12} \mathbf{u}_2^n) - \mathbf{u}_1^n \\ \begin{pmatrix} \mathbf{u}_1^{n+\frac{1}{2}} \\ \mathbf{u}_2^{n+\frac{1}{2}} \end{pmatrix} &= \begin{pmatrix} \mathbf{u}_1^n \\ \mathbf{u}_2^n \end{pmatrix} + \begin{pmatrix} A_1^{-1}(\mathbf{f}_1 - A_{12} \mathbf{u}_2^n) - \mathbf{u}_1^n \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} A_1^{-1}(\mathbf{f}_1 - A_{12} \mathbf{u}_2^n) \\ \mathbf{u}_2^n \end{pmatrix} \end{aligned}$$

## Relation with Alternating Schwarz

Similarly, from the second relation of MS, i.e.

$$\mathbf{u}^{n+1} = \mathbf{u}^{n+\frac{1}{2}} + R_2^T A_2^{-1} R_2 (\mathbf{f} - A \mathbf{u}^{n+\frac{1}{2}})$$

we obtain

$$\begin{pmatrix} \mathbf{u}_1^{n+1} \\ \mathbf{u}_2^{n+1} \end{pmatrix} = \begin{pmatrix} A_1^{-1} (\mathbf{f}_1 - A_{12} \mathbf{u}_2^n) \\ A_2^{-1} (\mathbf{f}_2 - A_{21} \mathbf{u}_1^{n+1}) \end{pmatrix},$$

which can be rewritten in the equivalent form

$$A_1 \mathbf{u}_1^{n+1} = \mathbf{f}_1 - A_{12} \mathbf{u}_2^n, \quad A_2 \mathbf{u}_2^{n+1} = \mathbf{f}_2 - A_{21} \mathbf{u}_1^{n+1}$$

and is therefore a discretization of the alternating Schwarz method from 1869,

$$\begin{aligned} \mathcal{L}u_1^{n+1} &= f, \text{ in } \Omega_1 & \mathcal{L}u_2^{n+1} &= f, \text{ in } \Omega_2 \\ u_1^{n+1} &= u_2^n, \text{ on } \Gamma_1 & u_2^{n+1} &= u_1^{n+1}, \text{ on } \Gamma_2 \end{aligned}$$

## MS is also a block Gauss Seidel method

MS is also equivalent to a block Gauss Seidel method, since

$$A_1 \mathbf{u}_1^{n+1} = \mathbf{f}_1 - A_{12} \mathbf{u}_2^n, \quad A_2 \mathbf{u}_2^{n+1} = \mathbf{f}_2 - A_{21} \mathbf{u}_1^{n+1}$$

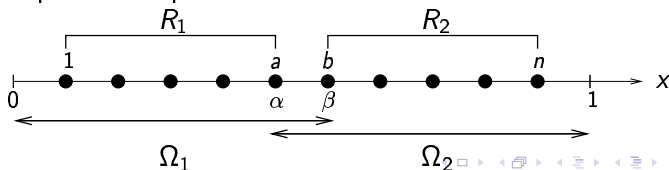
leads in matrix form to the iteration

$$\begin{bmatrix} A_1 & 0 \\ A_{21} & A_2 \end{bmatrix} \begin{pmatrix} \mathbf{u}_1^{n+1} \\ \mathbf{u}_2^{n+1} \end{pmatrix} = \begin{bmatrix} 0 & -A_{12} \\ 0 & 0 \end{bmatrix} \begin{pmatrix} \mathbf{u}_1^n \\ \mathbf{u}_2^n \end{pmatrix} + \begin{pmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \end{pmatrix}$$

### So why the complicated $R_j$ notation ?

- ▶ With  $R_j$ , one can also use overlapping blocks.
- ▶ With  $R_j$ , there is a global approximate solution  $\mathbf{u}^n$ .

Note that even the algebraically non-overlapping case above implies overlap at the PDE level:



# The Additive Schwarz Method (AS)

M. Drjya and O. Widlund 1989:

*The basic idea behind the additive form of the algorithm is to work with the simplest possible polynomial in the projections. Therefore the equation  $(P_1 + P_2 + \dots + P_N)u_h = g'_h$  is solved by an iterative method.*

Using the same notation as before, the preconditioned system is

$$(R_1^T A_1^{-1} R_1 + R_2^T A_2^{-1} R_2) A \mathbf{u} = (R_1^T A_1^{-1} R_1 + R_2^T A_2^{-1} R_2) \mathbf{f}$$

Writing this as a stationary iterative method yields

$$\mathbf{u}^n = \mathbf{u}^{n-1} + (R_1^T A_1^{-1} R_1 + R_2^T A_2^{-1} R_2) (\mathbf{f} - A \mathbf{u}^{n-1})$$

**Question:** Is AS equivalent to a discretization of Lions parallel Schwarz method ?

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## Algebraically non-overlapping case

If the  $R_j$  are non-overlapping, we obtain now

$$\begin{pmatrix} \mathbf{u}_1^{n+1} \\ \mathbf{u}_2^{n+1} \end{pmatrix} = \begin{pmatrix} A_1^{-1}(\mathbf{f}_1 - A_{12}\mathbf{u}_2^n) \\ A_2^{-1}(\mathbf{f}_2 - A_{21}\mathbf{u}_1^n) \end{pmatrix},$$

which can be rewritten in the equivalent form

$$A_1 \mathbf{u}_1^{n+1} = \mathbf{f}_1 - A_{12} \mathbf{u}_2^n, \quad A_2 \mathbf{u}_2^{n+1} = \mathbf{f}_2 - A_{21} \mathbf{u}_1^n.$$

This a discretization of Lions parallel Schwarz method from 1988,

$$\begin{aligned} \mathcal{L}u_1^{n+1} &= f, \text{ in } \Omega_1 & \mathcal{L}u_2^{n+1} &= f, \text{ in } \Omega_2 \\ u_1^{n+1} &= u_2^n, \text{ on } \Gamma_1 & u_2^{n+1} &= u_1^n, \text{ on } \Gamma_2 \end{aligned}$$

In the algebraically non-overlapping case, AS is also equivalent to a block Jacobi method,

$$\begin{bmatrix} A_1 & 0 \\ 0 & A_2 \end{bmatrix} \begin{pmatrix} \mathbf{u}_1^{n+1} \\ \mathbf{u}_2^{n+1} \end{pmatrix} = \begin{bmatrix} 0 & -A_{12} \\ -A_{21} & 0 \end{bmatrix} \begin{pmatrix} \mathbf{u}_1^n \\ \mathbf{u}_2^n \end{pmatrix} + \begin{pmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \end{pmatrix}$$

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## What happens if the $R_j$ overlap ?

If the  $R_j$  overlap, the cancellation is more complicated:

$$\mathbf{u}^{n+1} = \mathbf{u}^n + \begin{pmatrix} A_1^{-1}(\mathbf{f}_1 - A_{12}\mathbf{u}_2^n) - \mathbf{u}_1^n \\ \mathbf{0} \end{pmatrix} + \begin{pmatrix} \mathbf{0} \\ A_2^{-1}(\mathbf{f}_2 - A_{21}\mathbf{u}_1^n) - \mathbf{u}_2^n \end{pmatrix}.$$

In the overlap, the current iterate is subtracted twice, and a new approximation from the left and right solve is added.

### Remarks:

- ▶ One can show that the spectral radius of the AS iteration operator equals 1.
- ▶ The method converges outside of the overlap.

AS is thus not equivalent to a discretization of Lions parallel Schwarz method for more than minimal physical overlap.

# Fundamental Convergence Result

M. Drjya and O. Widlund 1989:

Including a coarse grid correction in the additive Schwarz preconditioner,

$$M_{AS} := \sum_{j=1}^n R_j^T A_j^{-1} R_j + R_0^T A_0^{-1} R_0$$

with characteristic coarse mesh size  $H$  and overlap  $\delta$ , one can show

## Theorem

*The condition number of the additive Schwarz preconditioned system satisfies*

$$\kappa(M_{AS}A) \leq C \left( 1 + \frac{H}{\delta} \right),$$

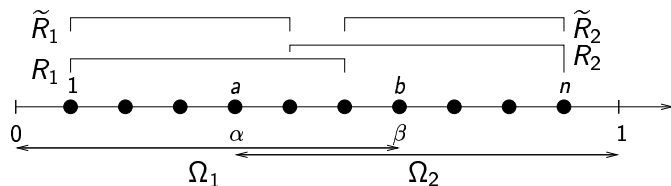
*where the constant  $C$  is independent of  $\delta$  and  $H$ .*

# Restricted Additive Schwarz (RAS)

X. Cai and M. Sarkis 1998:

*While working on an AS/GMRES algorithm in an Euler simulation, we removed part of the communication routine and surprisingly the “then AS” method converged faster in both terms of iteration counts and CPU time.*

$$u^{n+1} = u^n + (\tilde{R}_1^T A_1^{-1} R_1 + \tilde{R}_2^T A_2^{-1} R_2)(f - Au^n)$$



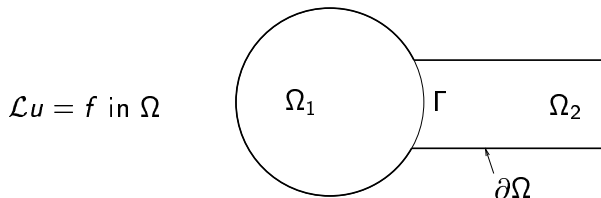
## Remarks:

- ▶ RAS is equivalent to a discretization of Lions parallel Schwarz method (Efsthathiou, G. 2003)
- ▶ the preconditioner is **non symmetric**, even if  $A_j$  is symmetric

# Problems of classical Schwarz: Overlap Necessary

P-L. Lions 1990:

*However, the Schwarz method requires that the subdomains overlap, and this may be a severe restriction - without speaking of the obvious or intuitive waste of efforts in the region shared by the subdomains.*

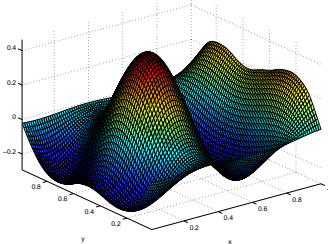
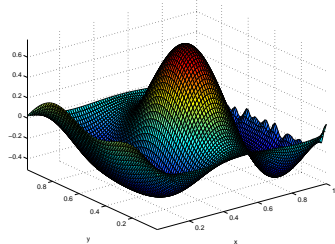
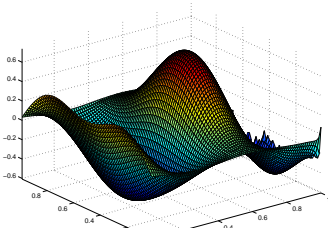
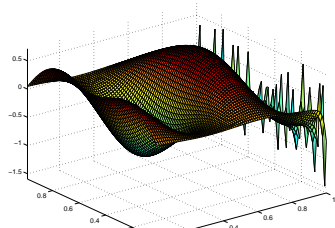


$$\begin{aligned} \mathcal{L}u_1^n &= f & \text{in } \Omega_1 & & \mathcal{L}u_2^n &= f & \text{in } \Omega_2 \\ (\partial_{n_1} + p_1)u_1^n &= (\partial_{n_1} + p_1)u_2^{n-1} & \text{on } \Gamma & & (\partial_{n_2} + p_2)u_2^n &= (\partial_{n_2} + p_2)u_1^n & \text{on } \Gamma \end{aligned}$$

P-L. Lions 1990:

*First of all, it is possible to replace the constants in the Robin conditions by two proportional functions on the interface, or even by local or nonlocal operators.*

# Other Problem: Lack of Convergence



B. Després 1990:

*L'objectif de ce travail est, après construction d'une méthode de décomposition de domaine adaptée au problème de Helmholtz, d'en démontrer la convergence.*

# Further Problem: Convergence Speed

T. Hagstrom, R. P. Tewarson and A. Jazcilevich 1988:  
Numerical experiments on a domain decomposition  
algorithm for nonlinear elliptic boundary value problems

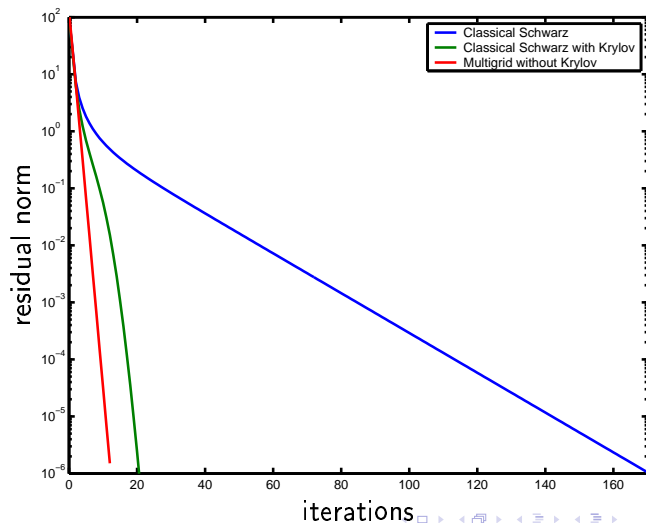
*In general, [the coefficients in the Robin transmission conditions] may be operators in an appropriate space of function on the boundary. Indeed, we advocate the use of nonlocal conditions.*

W.-P. Tang 1992: Generalized Schwarz Splittings

*In this paper, a new coupling between the overlap[ping] subregions is identified. If a successful coupling is chosen, a fast convergence of the alternating process can be achieved without a large overlap.*

# Comparison of Classical Schwarz with Multigrid

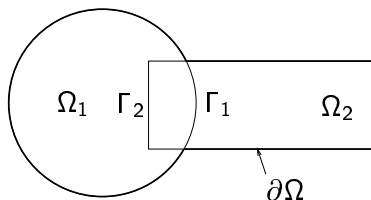
Comparison of MS with two subdomains as an iterative solver and a preconditioner for a Krylov method, with a standard multigrid solver:





# Continuous Optimized Schwarz Methods

$$\mathcal{L}u = f \text{ in } \Omega$$



Instead of the classical alternating Schwarz method

$$\begin{aligned} \mathcal{L}u_1^n &= f, \text{ in } \Omega_1 & \mathcal{L}u_2^n &= f, \text{ in } \Omega_2 \\ u_1^n &= u_2^{n-1}, \text{ on } \Gamma_1 & u_2^n &= u_1^n, \text{ on } \Gamma_2 \end{aligned}$$

one uses transmission conditions adapted to the PDE,

$$\mathcal{B}_1 u_1^n = \mathcal{B}_1 u_2^{n-1}, \text{ on } \Gamma_1 \quad \mathcal{B}_2 u_2^n = \mathcal{B}_2 u_1^n, \text{ on } \Gamma_2$$

## Remarks:

- ▶ optimal choice for  $\mathcal{B}_j$  is  $\partial_{n_j} + DtN_j$
- ▶ good approximation is  $\mathcal{B}_j = \partial_{n_j} + p_j + r_j \partial_\tau + q_j \partial_{\tau\tau}$
- ▶ method can converge even without physical overlap

# How to choose the parameters

Contraction factor using Fourier analysis:

$$\rho(z, s) = \left( \frac{s(z) - f_{PDE}(z)}{s(z) + f_{PDE}(z)} \right)^2 e^{-L f_{PDE}(z)}$$

- ▶  $z$  related to the Fourier parameters
- ▶  $s$  polynomial with coefficients to be optimized.
- ▶  $f_{PDE}$  symbol of the DtN of the PDE to be solved.

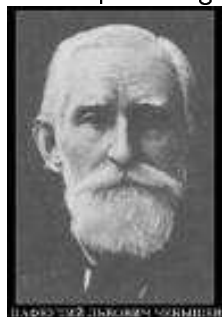
For a fast algorithm, we need to minimize  $\rho$ , i.e.

$$\inf_{s \in \mathbb{P}_n} \sup_{z \in K} |\rho(z, s)|$$

- ▶  $\mathbb{P}_n$  set of complex polynomials of degree  $\leq n$
- ▶  $K$  is a bounded or unbounded set in the complex plane

# Best Approximation Problems

**Chebyshev (1854):** Théorie des mécanismes connus sous le nom de parallélogrammes.



$$\min_{p \in \mathbb{P}_n} \max_{x \in K} |f(x) - p(x)|$$

... la différence  $f(x) - p$  jouira, **comme on le sait**, de cette propriété: Parmi les valeurs les plus grandes et les plus petites de la différence  $f(x) - p$  entre les limites, on trouve au moins  $n + 2$  fois la même valeur numérique.

## Theorem (Bennequin, G, Halpern 2005)

If  $L = 0$  and  $K$  is compact, then for every  $n \geq 0$ , there exists a unique solution  $s_n^*$ , and there exist at least  $n + 2$  points  $z_1, \dots, z_{n+2}$  in  $K$  such that

$$\left| \frac{s_n^*(z_i) - f(z_i)}{s_n^*(z_i) + f(z_i)} \right| = \left\| \frac{s_n^* - f}{s_n^* + f} \right\|_\infty$$

## Case $L > 0$

Without assuming that  $K$  is compact, one can show (Bennequin, G, Halpern 2006):

### Theorem (Existence)

Let  $K$  be a closed set in  $\mathbb{C}$ , containing at least  $n + 2$  points. Let  $f$  satisfy  $\Re f(z) > 0$  and

$$\Re f(z) \rightarrow +\infty \text{ as } z \rightarrow \infty \text{ in } K.$$

Then for  $L$  small enough, there exists a solution.

### Theorem (Equioscillation)

Under the same assumptions, if  $s_n^*$  is a solution for  $L > 0$ , then there exist at least  $n + 2$  points  $z_1, \dots, z_{n+2}$  in  $K$  such that

$$\left| \frac{s_n^*(z_i) - f(z_i)}{s_n^*(z_i) + f(z_i)} e^{-Lf(z_i)} \right| = \left\| \frac{s_n^* - f}{s_n^* + f} e^{-Lf} \right\|_{\infty} = \delta_n(L)$$

# Uniqueness, Local Minima and Symmetry

## Theorem (Uniqueness)

With the same assumptions, *and if  $K$  is compact*, and  $L$  satisfies

$$\delta_n(L) e^{L \sup_{z \in K} \Re f(z)} < 1,$$

where  $\delta_n(L)$  is the minimum, then the solution is unique.

## Theorem (Local Minima)

*If  $K$  is compact*, and  $L$  is small, then if  $s_n^*$  is a strict local minimum, then it is the global minimum.

## Theorem (Symmetry $\implies$ real coefficients)

*If  $K$  is compact* and symmetric with respect to the  $x$ -axis, and  $f(\bar{z}) = \overline{f(z)}$  in  $K$ , then for  $L$  small,  $s_n^*$  has real coefficients.

# Optimized Parameters for a Model Problem

For the self adjoint coercive problem

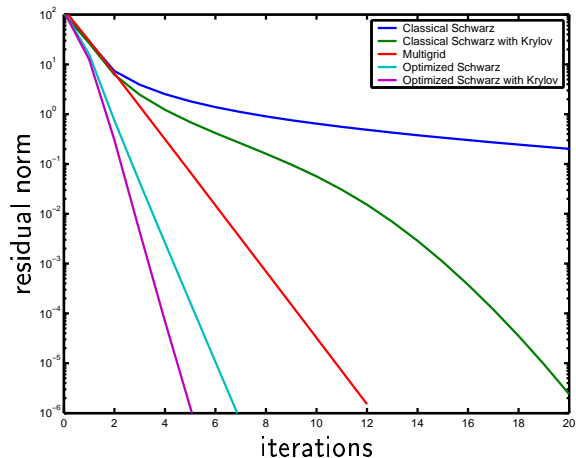
$$\mathcal{L}u = (\eta - \Delta)u = f$$

the asymptotically optimal parameters are (G 2006)

	$p$	$q$
OO0	$\frac{\sqrt{\pi}(k_{\min}^2 + \eta)^{1/4}}{h^{1/2}}$	0
OO0(Ch)	$\frac{(k_{\min}^2 + \eta)^{1/3}}{2^{1/3}(Ch)^{1/3}}$	0
OO2	$\frac{\pi^{1/4}(k_{\min}^2 + \eta)^{3/8}}{2^{1/2}h^{1/4}}$	$h^{3/4}$
OO2(Ch)	$\frac{(k_{\min}^2 + \eta)^{2/5}}{2^{3/5}(Ch)^{1/5}}$	$\frac{2^{1/2}\pi^{3/4}(k_{\min}^2 + \eta)^{1/8}}{(Ch)^{3/5}}$
TO0	$\sqrt{\eta}$	0
TO2	$\sqrt{\eta}$	$\frac{1}{2\sqrt{\eta}}$

# Comparison of Optimized Schwarz with Multigrid

Comparison of MS as an iterative solver, as a preconditioner, multigrid, and an optimized Schwarz methods used iteratively and as a preconditioner:



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# Discrete Optimized Schwarz Methods

How does one have to change the RAS

$$M_{RAS}^{-1} = (\tilde{R}_1^T A_1^{-1} R_1 + \tilde{R}_2^T A_2^{-1} R_2)$$

and the MS preconditioner

$$M_{MS}^{-1} = \left[ I - \prod_{j=1}^J \left( I - R_j^T A_j^{-1} R_j A \right) \right] A^{-1},$$

to obtain an optimized method ?

**Simply replace  $A_j$  by a slightly modified  $\tilde{A}_j$  !**

(St-Cyr, G and Thomas, 2007)



# An Example

$$\mathcal{L}u = (\eta - \Delta)u = f, \quad \text{in } (0, 1)^2$$

Finite volume discretization leads to

$$A\mathbf{u} = \mathbf{f}$$

$$A = \frac{1}{h^2} \begin{bmatrix} T_\eta & -I & & \\ -I & T_\eta & \ddots & \\ & \ddots & \ddots & \ddots \end{bmatrix}, \quad T_\eta = \begin{bmatrix} \eta h^2 + 4 & -1 & & \\ -1 & \eta h^2 + 4 & \ddots & \\ & \ddots & \ddots & \ddots \end{bmatrix}$$

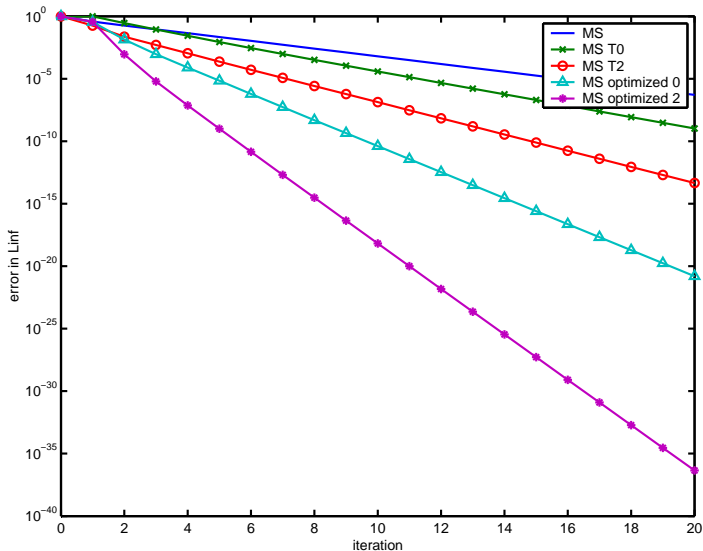
The classical subdomain matrices are  $A_j = R_j A R_j^T$ .

The optimized  $\tilde{A}_j$  are obtained from  $A_j$  by simply replacing the interface diagonal block  $T_\eta$  by

$$\tilde{T} = \frac{1}{2} T_\eta + p h I + \frac{q}{h} (T_0 - 2I), \quad T_0 = T_\eta|_{\eta=0},$$

where  $p$  and  $q$  are solutions of the associated min-max problem.

# Result for the Example



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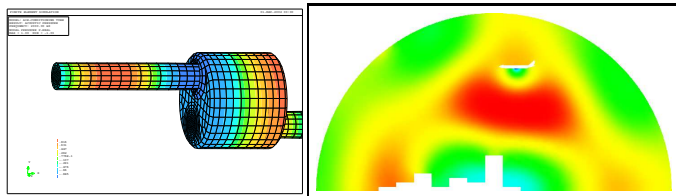
# Results for other PDEs

Such formulas are also available for advection-reaction-diffusion (Japhet 1998, Dubois and G. 2007), Helmholtz (Chevalier 1998, G., Magoules, Nataf 2001), Heat (G. Halpern 2003), Wave (G., Halpern, Nataf 2003), Cauchy-Riemann and Maxwell's equations (Dolean, G., Gerardo-Giorda 2007)

Case	with overlap, $L = h$		without overlap, $L = 0$	
	$\rho$	parameters	$\rho$	parameters
1	$1 - \sqrt{k_+ - \omega^2} h$	none	1	none
2	$1 - 2C_\omega^{\frac{1}{6}} h^{\frac{1}{3}}$	$p = \frac{C_\omega^{\frac{1}{3}}}{2 \cdot h^{\frac{1}{3}}}$	$1 - \frac{\sqrt{2} C_\omega^{\frac{1}{4}}}{\sqrt{C}} \sqrt{h}$	$p = \frac{\sqrt{C} C_\omega^{\frac{1}{4}}}{\sqrt{2} \sqrt{h}}$
3	$1 - 2(k_+^2 - \omega^2)^{\frac{1}{6}} h^{\frac{1}{3}}$	$p = \frac{(k_+^2 - \omega^2)^{\frac{1}{3}}}{2 \cdot h^{\frac{1}{3}}}$	$1 - \frac{\sqrt{2}(k_+^2 - \omega^2)^{\frac{1}{4}}}{\sqrt{C}} \sqrt{h}$	$p = \frac{\sqrt{C}(k_+^2 - \omega^2)^{\frac{1}{4}}}{\sqrt{2} \sqrt{h}}$
4	$1 - 2^{\frac{2}{5}} C_\omega^{\frac{1}{10}} h^{\frac{1}{5}}$	$\left\{ \begin{array}{l} p_1 = \frac{C_\omega^{\frac{1}{5}}}{2^{\frac{1}{5}} \cdot h^{\frac{1}{5}}} \\ p_2 = \frac{C_\omega^{\frac{1}{5}}}{2^{\frac{6}{5}} \cdot h^{\frac{3}{5}}} \end{array} \right.$	$1 - \frac{C_\omega^{\frac{1}{8}}}{C^{\frac{1}{4}}} h^{\frac{1}{4}}$	$\left\{ \begin{array}{l} p_1 = \frac{C_\omega^{\frac{3}{8}} \cdot C^{\frac{1}{4}}}{2 \cdot h^{\frac{1}{4}}} \\ p_2 = \frac{C_\omega^{\frac{3}{8}} \cdot C^{\frac{3}{4}}}{h^{\frac{3}{4}}} \end{array} \right.$
5	$1 - 2^{\frac{2}{5}} (k_+^2 - \omega^2)^{\frac{1}{10}} h^{\frac{1}{5}}$	$\left\{ \begin{array}{l} p_1 = \frac{(k_+^2 - \omega^2)^{\frac{2}{5}}}{2^{\frac{1}{5}} \cdot h^{\frac{1}{5}}} \\ p_2 = \frac{(k_+^2 - \omega^2)^{\frac{1}{5}}}{2^{\frac{6}{5}} \cdot h^{\frac{3}{5}}} \end{array} \right.$	$1 - \frac{(k_+^2 - \omega^2)^{\frac{1}{8}}}{C^{\frac{1}{4}}} h^{\frac{1}{4}}$	$\left\{ \begin{array}{l} p_1 = \frac{(k_+^2 - \omega^2)^{\frac{3}{8}} \cdot C^{\frac{1}{4}}}{2 \cdot h^{\frac{1}{4}}} \\ p_2 = \frac{(k_+^2 - \omega^2)^{\frac{1}{8}} \cdot C^{\frac{3}{4}}}{h^{\frac{3}{4}}} \end{array} \right.$

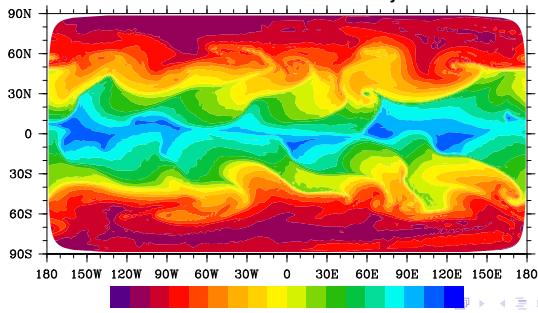
# Large Scale Optimized Schwarz Computations

- ▶ Exhaust system, and airplane in approach over a city:



- ▶ Held Suarez test, temperature field, at the surface of the planet after 200 days of simulation.

T at level = 19 time=200 days



Optimized  
Schwarz Methods

Martin J. Gander

Classical Schwarz

Continuous

Discrete

Problems of

Classical Schwarz

Overlap Required

No Convergence

Convergence Speed

Optimized Schwarz

Continuous

Discrete

Applications

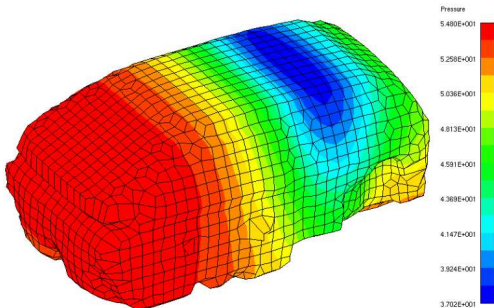
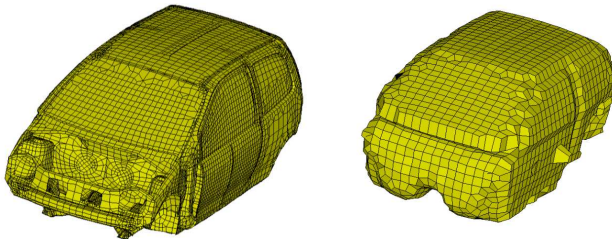
Airplane, Climate

Twingo

Conclusions

# Large Scale Optimized Schwarz Computations

- ▶ Twingo, noise simulation in the passenger compartment:



Optimized  
Schwarz Methods

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Classical Schwarz

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Discrete

Applications

Airplane, Climate

**Twingo**

Conclusions

# Conclusions

- ▶ Discrete Schwarz methods are in most cases discretizations of continuous Schwarz methods (exception: AS with overlap!)
- ▶ Optimized Schwarz Methods use transmission conditions adapted to the underlying PDE, which can greatly improve their convergence rate
- ▶ Replacing classical subdomain matrices  $A_i$  by optimized ones, leads to optimized MS, RAS and AS (on an augmented system)

## Important open problems: (2007)

- ▶ General convergence proof for overlapping optimized Schwarz
- ▶ Coarse grid corrections for optimized Schwarz
- ▶ Algebraically optimized  $\tilde{A}_i$