

An application of the Bauer-Fike theorem to nonlinear eigenproblems

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joint work with Johan Karlsson, KTH

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Eigenvalue perturbation: Given $A_1, A_2 \in \mathbb{R}^{n \times n}$

$$\lambda_1 \in \sigma(A_1)$$

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Introduction:

- Nonlinear eigenvalue problems
- the Bauer-Fike Theorem
- Accuracy iteration

Nonlinear eigenproblems

Quadratic eigenproblem:

Linearization[MMMM'06], SOAR[Bai,Su'05], JD[Slejpen et al'96]

$$0 = (A - \lambda I + \lambda^2 B) v$$

$$\lambda \in \sigma(A + B\lambda^2)$$

Nonlinear eigenproblems

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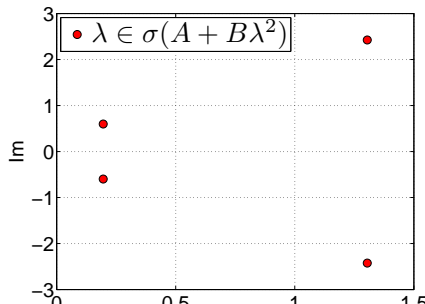
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Example:

$$A = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}, B = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix}$$



Nonlinear eigenproblems

Delay eigenvalue problem:

LMS[Engelborghs, et al'99], Pseudospectral differencing[Breda, et al'05]

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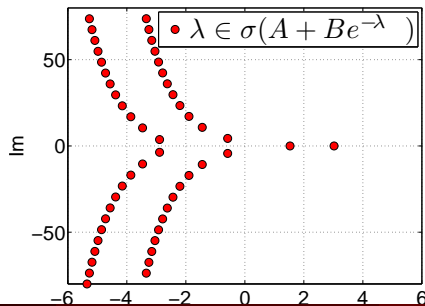
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The Bauer-Fike Theorem [Bauer,Fike'60]

Classical formulation

Theorem (BF)

If $A_1 = V_1 D_1 V_1^{-1}$ then for any $\lambda_2 \in \sigma(A_2)$

$$\min_{\lambda_1 \in \sigma(A_1)} |\lambda_2 - \lambda_1| \leq \kappa(V_1) \|A_1 - A_2\|.$$

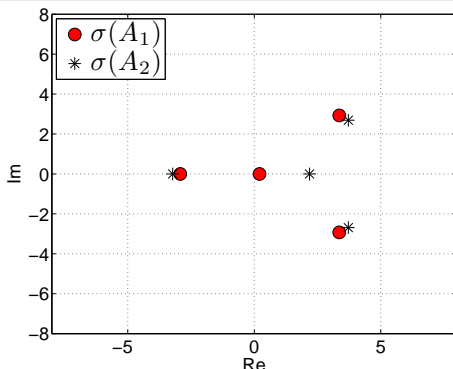
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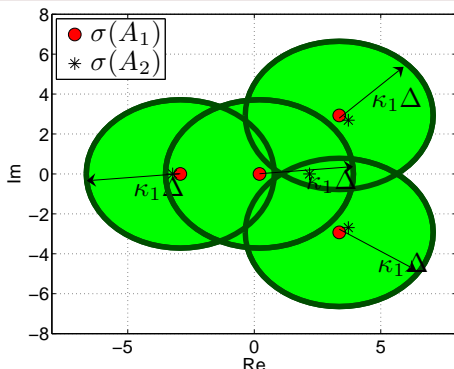
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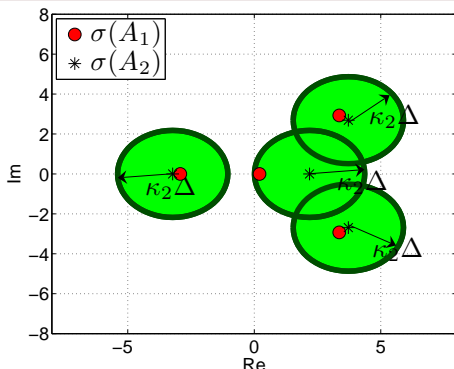
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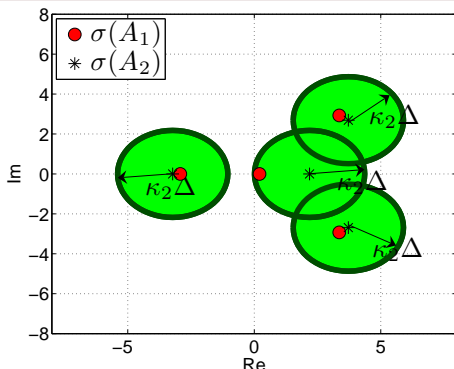
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If $A_2 = V_2 D_2 V_2^{-1}$ then for any $\lambda_1 \in \sigma(A_1)$

$$\text{dist}(\lambda_1, \sigma(A_2)) := \min_{\lambda_2 \in \sigma(A_2)} |\lambda_2 - \lambda_1| \leq \kappa(V_2) \|A_1 - A_2\|.$$



The Bauer-Fike Theorem

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If $\lambda_1 \in \sigma(A_1)$ and $\lambda_2 \in \sigma(A_2)$ then

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where $\text{dist}(\lambda, S) = \min_{s \in S} |\lambda - s|$.

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For the Hausdorff metric

$$d_H(S_1, S_2) := \max \left(\max_{s_1 \in S_1} \text{dist}(s_1, S_2), \max_{s_2 \in S_2} \text{dist}(s_2, S_1) \right)$$

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Theorem (BF - Hausdorff metric)

$$d_H(\sigma(A_1), \sigma(A_2)) \leq \max(\kappa(V_1), \kappa(V_2)) \|A_1 - A_2\|$$

- Perturbation of polynomial eigenvalue problems:
 - [Tisseur'00] (backward error)
 - [Higham, Tisseur'03]
 - [Chu,Lin'04] (Bauer-Fike)
 - [Dedieu, Tisseur'03]
 - [Karow,Kressner,Tisseur'06] (condition number)
- Nonlinear eigenvalue problems:
 - [Haderl '69] (generalized Rayleigh-functionals)
 - [Ehrmann '65]
 - [Cullum, Ruehli '01] (pseudospectra)
 - [Wagenknecht,Michiels,Green'07] (pseudospectra)

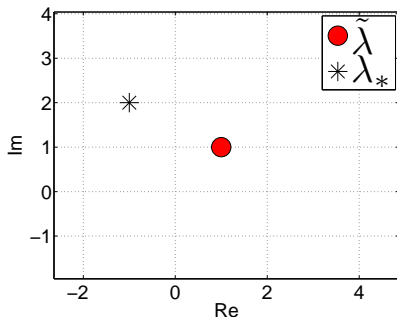
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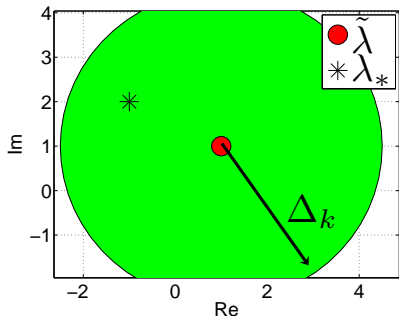


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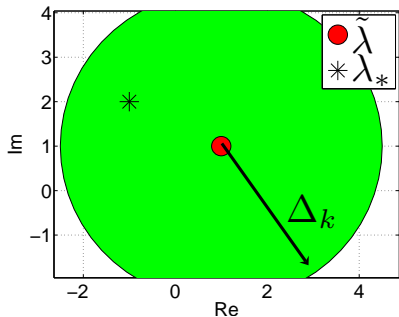
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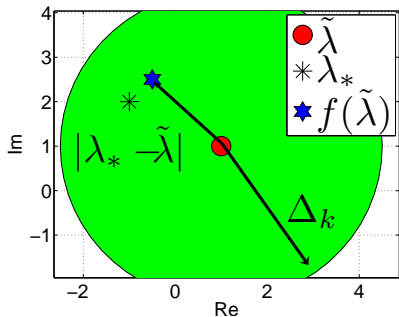
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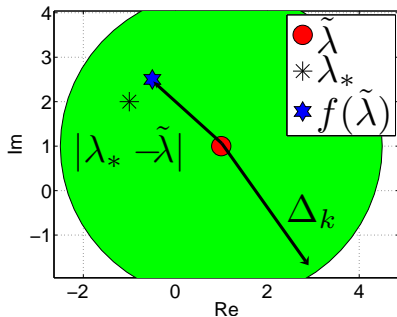
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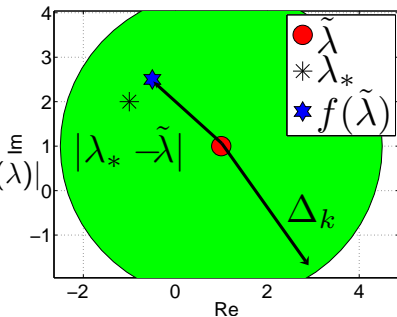
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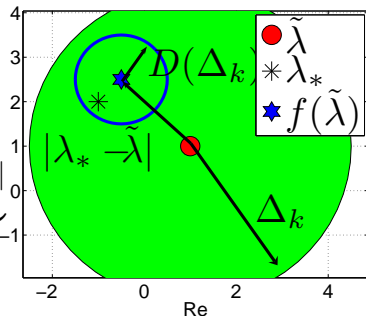
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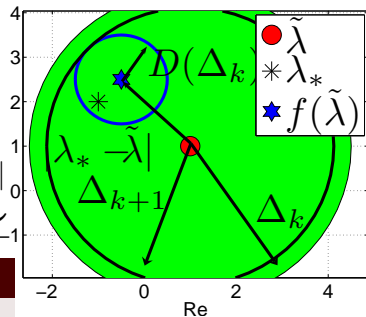
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Accuracy Fixpoint Iteration

$\lambda_* \in V(\Delta_k) \Rightarrow \lambda_* \in V(\Delta_{k+1})$ where

$$\Delta_{k+1} = \varphi(\Delta_k) := |\tilde{\lambda} - f(\tilde{\lambda})| + D(\Delta_k)$$

Example

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$$D(\Delta_k) = \max_{\lambda \in V(\Delta_k)} |f(\lambda) - f(\tilde{\lambda})| = 0.2\Delta_k + 0.1\Delta_k^2$$

$$\Delta_{k+1} = \phi(\Delta_k) = 0.1 + 0.2\Delta_k + 0.1\Delta_k^2$$

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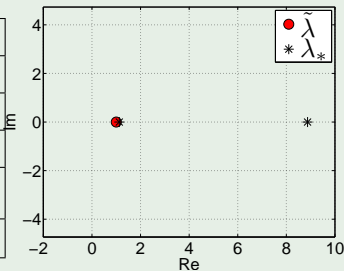
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$\Delta_1 = \phi(\Delta_0)$	0.9
$\Delta_2 = \phi(\Delta_1)$	0.361
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\vdots	\vdots
Δ_*	$4 - \sqrt{4^2 - 1} \approx 0.127$



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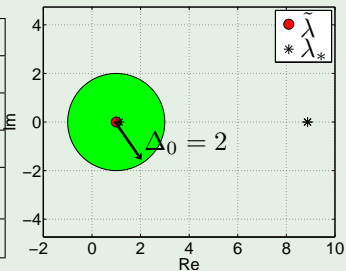
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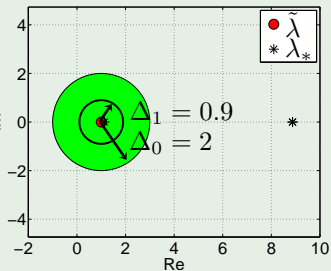
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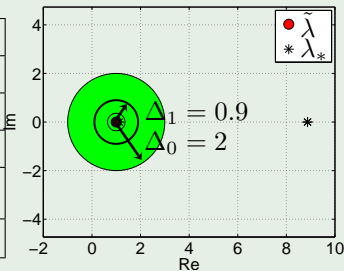
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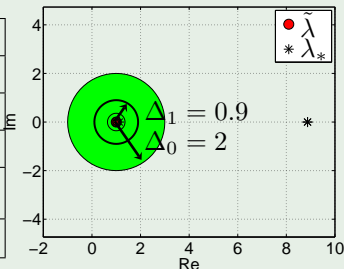
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Error of $\tilde{\lambda}$ less than $\Delta_0 = 2 \Rightarrow$ error less than $\Delta_* = 0.127$.

Main results:

- A BF-NLVP comparison theorem
- Accuracy iteration with **constant comparison**
- Accuracy iteration with **linear comparison**
- Accuracy iteration with **linear normalized comparison**

Theorem (BF-NLEVP - General comparison)

Let $\lambda_1 \in \sigma(G_1(\lambda_1))$, $\lambda_2 \in \sigma(G_2(\lambda_2))$ and

$$\|G_1(\lambda) - G_2(\lambda)\| \leq \delta, \|G'_1(\lambda)\| \leq \varepsilon_1, \|G'_2(\lambda)\| \leq \varepsilon_2.$$

for all $\lambda \in V$. Then,

$$a) \quad |\lambda_1 - \lambda_2| \leq \frac{\kappa_2}{1 - \kappa_2 \varepsilon_2} \delta$$

$$b) \quad |\lambda_1 - \lambda_2| \leq \frac{\kappa_1}{1 - \kappa_1 \varepsilon_1} \delta$$

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for all $\lambda \in V$. Then,

- a) $\lambda_2 = \operatorname{argmin}_{\lambda \in \sigma(G_2(\lambda_2))} |\lambda - \lambda_1| \Rightarrow |\lambda_1 - \lambda_2| \leq \frac{\kappa_2}{1 - \kappa_2 \varepsilon_2} \delta$
- b) $\lambda_1 = \operatorname{argmin}_{\lambda \in \sigma(G_1(\lambda_1))} |\lambda - \lambda_2| \Rightarrow |\lambda_1 - \lambda_2| \leq \frac{\kappa_1}{1 - \kappa_1 \varepsilon_1} \delta$

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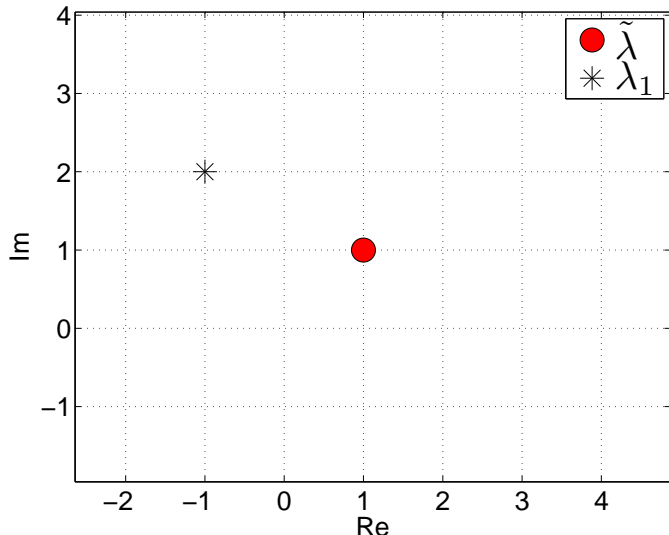
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- b) $\lambda_1 = \operatorname{argmin}_{\lambda \in \sigma(G_1(\lambda_1))} |\lambda - \lambda_2| \Rightarrow |\lambda_1 - \lambda_2| \leq \frac{\kappa_1}{1 - \kappa_1 \varepsilon_1} \delta$

Pf. Sketch.

$$\begin{aligned} |\lambda_1 - \lambda_2| &\stackrel{BF}{\leq} \kappa_1 \|G_1(\lambda_1) - G_2(\lambda_2)\| \\ &\leq \kappa_1 (\|G_1(\lambda_1) - G_1(\lambda_2)\| + \|G_2(\lambda_2) - G_1(\lambda_2)\|) \\ &\leq \kappa_1 (\varepsilon_1 |\lambda_1 - \lambda_2| + \delta) \Rightarrow |\lambda_1 - \lambda_2| \leq \frac{\kappa_1}{1 - \kappa_1 \varepsilon_1} \delta \end{aligned}$$

Accuracy iteration (constant comparison)

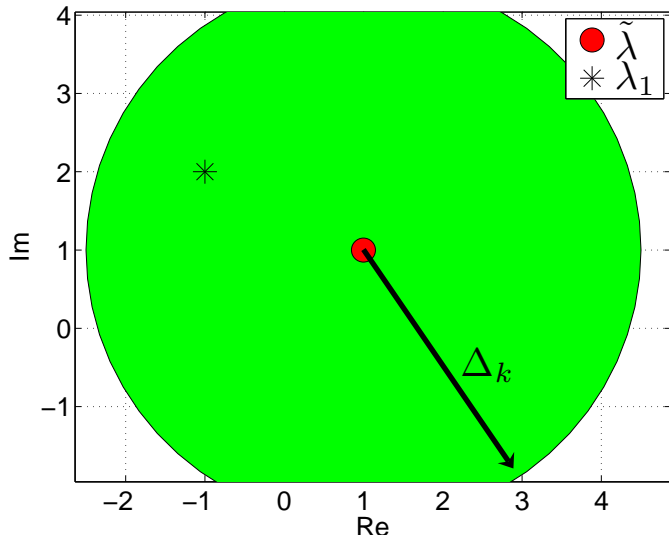
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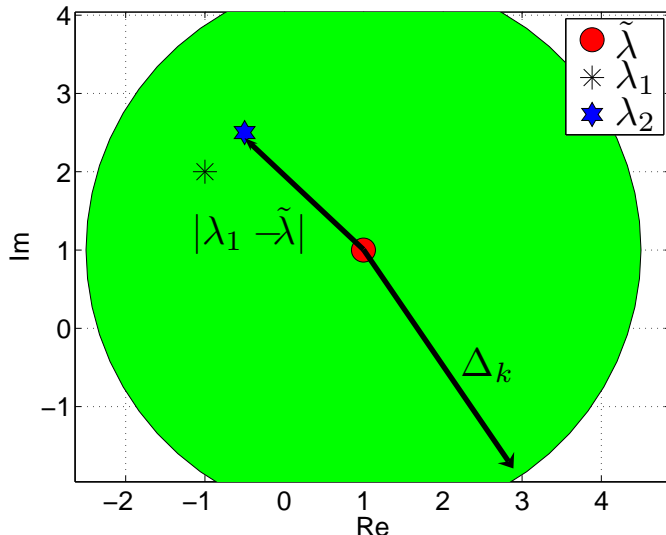
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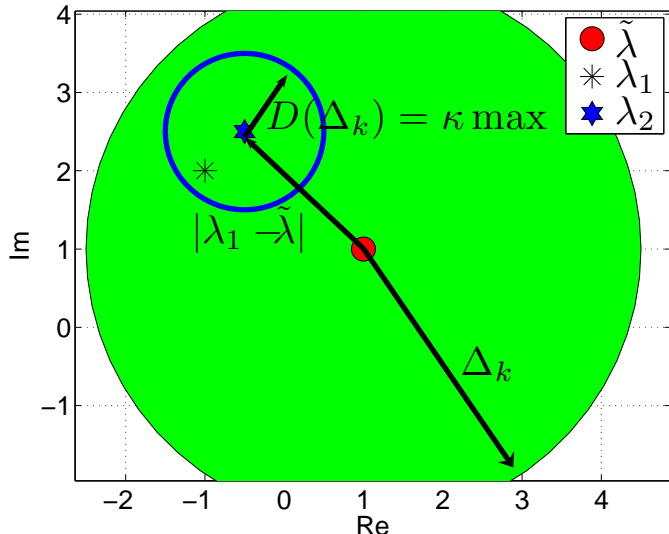
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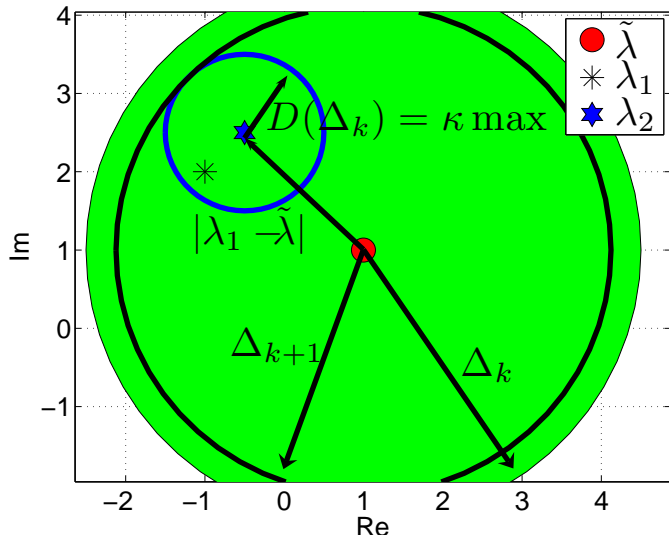
Assume $\lambda_1 \in V(\Delta_k)$. Define $\lambda_2 \in \sigma(G(\tilde{\lambda}))$. Use BF-NLEVP to bound $|\lambda_1 - \lambda_2| < D(\Delta_k)$.



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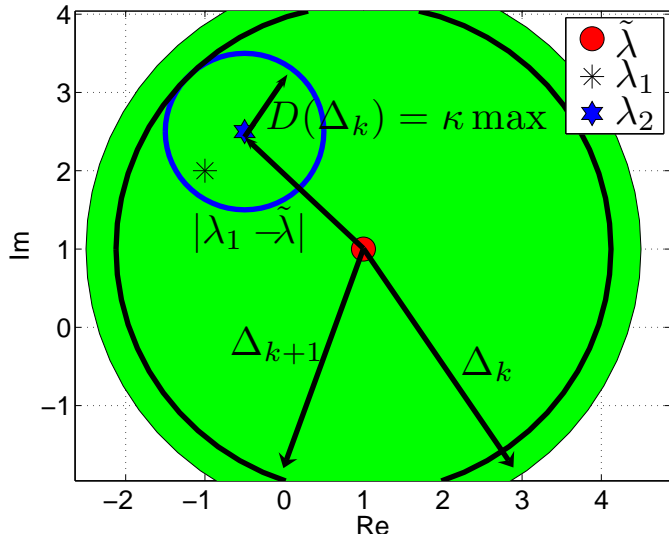
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Iteration

If $\lambda_1 \in V(\Delta_k) \Rightarrow \lambda_1 \in V(\Delta_{k+1})$ where

$$\Delta_{k+1} = |\tilde{\lambda} - \lambda_2| + \kappa_2 \max_{\lambda \in V(\Delta_k)} \|G(\lambda) - G(\tilde{\lambda})\|$$

Cubic toy example

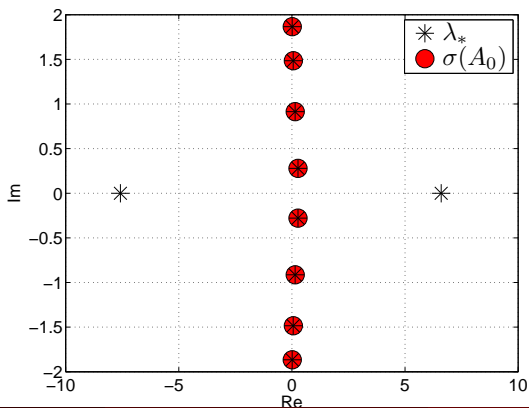
$$A_0 = \begin{pmatrix} 1 & -1 & & & & & & & \\ 1 & & -1 & & & & & & \\ & 1 & & -1 & & & & & \\ & & 1 & & -1 & & & & \\ & & & 1 & & -1 & & & \\ & & & & 1 & & -1 & & \\ & & & & & 1 & & -1 & \\ & & & & & & 1 & & -1 \\ & & & & & & & 1 & & -1 \end{pmatrix}, A_1 = \begin{pmatrix} 0.02 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix},$$

$$\lambda_* \in \sigma(A_0 + A_1 \lambda_*^3)$$

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Given approximation $\tilde{\lambda}$ we compute $\lambda_2 \in \sigma(A_0 + A_1 \tilde{\lambda}^3)$

$$\begin{aligned} \Delta_{k+1} &= |\lambda_2 - \tilde{\lambda}| + \kappa_2 \|A_1\| \max_{\lambda \in V(\Delta_k)} |\lambda^3 - \tilde{\lambda}^3| = \\ &= |\lambda_2 - \tilde{\lambda}| + \kappa_2 \|A_1\| \left((|\tilde{\lambda}| + \Delta_k)^3 - |\tilde{\lambda}|^3 \right) \end{aligned}$$

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λ_*	$\tilde{\lambda}$	$ \lambda_* - \tilde{\lambda} $	$\Delta_*^{(0)}$
$0.2721 \pm 0.2792i$	$0.2722 \pm 0.2787i$	5.82e-04	6.02e-04
$0.1447 \pm 0.9138i$	$0.1478 \pm 0.9135i$	3.09e-03	3.89e-03
$0.0596 \pm 1.4842i$	$0.0640 \pm 1.4848i$	4.49e-03	9.44e-03
$0.0140 \pm 1.8660i$	$0.0160 \pm 1.8664i$	1.99e-03	1.20e-02
6.5989			
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Accuracy iteration (linear comparison)

Compute one step of “Newton” (MSLP): $\lambda_2 \in \sigma(G(\tilde{\lambda}) + (\lambda_2 - \tilde{\lambda})G'(\tilde{\lambda}))$.

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For cubic toy example:

$$\Delta_{k+1} = |\lambda_2 - \tilde{\lambda}| + \frac{\kappa_2}{1 - 3\kappa_2 |\tilde{\lambda}|^2 \|A_1\|} \|A_1\| \max_{\lambda \in V(\Delta_k)} |\lambda^3 - \tilde{\lambda}^3 - 3(\lambda - \tilde{\lambda})\tilde{\lambda}^2|$$

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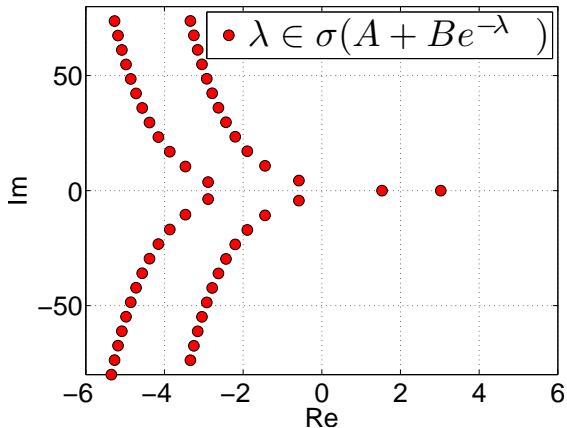
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Example (DDE)

$$\lambda_* \in \sigma \left(\begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} + \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix} e^{-\lambda_*} \right)$$

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Pick $\tilde{\lambda}$ as first LMS-approximation in DDE-BIFTOOL

λ_*	?	?	?	?	?
$\tilde{\lambda}$	1.5326	3.0246	-0.58±4.35i	-1.44±10.76i	-1.89±17.11i
$ \lambda_* - \tilde{\lambda} $?	?	?	?	?

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Normalization

$$\lambda \in \sigma(G(\lambda)) \Leftrightarrow \lambda \in \sigma \underbrace{\left((I - A)^{-1} (G(\lambda) - \lambda A) \right)}_{=: H(\lambda)}$$

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Let $A = G'(\tilde{\lambda})$ then $H'(\tilde{\lambda}) = 0 \Rightarrow \frac{\kappa_2}{1 - \kappa_2 \varepsilon_2} = \kappa_2$

- A *Bauer-Fike comparison theorem* for nonlinear eigenvalue problems
- Accuracy of solutions *nonlinear eigenvalue problems* with a accuracy iterations
- Future: Relation to *method of linear/constant problems*

