# Computing the Norm $\|A\|_{\infty, 1}$ is NP-Hard 

## Dedicated to Professor Svatopluk Poljak, in memoriam

Jiří Rohn*


#### Abstract

It is proved that computing the subordinate matrix norm $\|A\|_{\infty, 1}$ is NP-hard. Even more, existence of a polynomial-time algorithm for computing this norm with relative accuracy less than $1 /\left(4 n^{2}\right)$, where $n$ is matrix size, implies $\mathrm{P}=\mathrm{NP}$.


Key words. Norm, positive definiteness, $M$-matrix, NP-hardness

AMS subject classifications. 15A57, 15A60, 15A63, 90C60

## 1 Introduction

Given two vector norms $\|x\|_{\alpha}$ in $R^{n}$ and $\|x\|_{\beta}$ in $R^{m}$, a subordinate matrix norm in $R^{m \times n}$ is defined by

$$
\|A\|_{\alpha, \beta}=\max _{\|x\|_{\alpha}=1}\|A x\|_{\beta}
$$

(Golub and van Loan [4]). $\|A\|_{\alpha, \beta}$ is a matrix norm, i.e., it possesses the three usual properties: 1) $\|A\|_{\alpha, \beta} \geq 0$ and $\|A\|_{\alpha, \beta}=0$ if and only if $\left.A=0,2\right)\|A+B\|_{\alpha, \beta} \leq$ $\left.\|A\|_{\alpha, \beta}+\|B\|_{\alpha, \beta}, 3\right)\|\lambda A\|_{\alpha, \beta}=|\lambda| \cdot\|A\|_{\alpha, \beta}$. However, generally it does not possess the property $\|A B\|_{\alpha, \beta} \leq\|A\|_{\alpha, \beta}\|B\|_{\alpha, \beta}$ (it does e.g. if $\alpha=\beta$ ).

By combining the two frequently used norms

$$
\begin{aligned}
& \|x\|_{1}=\sum_{i}\left|x_{i}\right|, \\
& \|x\|_{\infty}=\max _{i}\left|x_{i}\right|,
\end{aligned}
$$

we get three well-known easily computable subordinate norms

$$
\begin{aligned}
& \|A\|_{1,1}=\max _{j} \sum_{i}\left|a_{i j}\right|, \\
& \|A\|_{\infty, \infty}=\max _{i} \sum_{j}\left|a_{i j}\right|, \\
& \|A\|_{1, \infty}=\max _{i j}\left|a_{i j}\right|
\end{aligned}
$$

[^0](see Golub and van Loan [4]). It turns out, however, that the fourth norm
$$
\|A\|_{\infty, 1}=\max _{\|x\|_{\infty}=1}\|A x\|_{1}
$$
has an exceptional behavior since it is much more difficult to compute. In this paper we prove that computing $\|A\|_{\infty, 1}$ is NP-hard. For the purpose of various applications, the result is presented in several different settings (Theorems 3 to 6 ).

## 2 The norm $\|A\|_{\infty, 1}$

This norm can be computed by a finite formula which, however, involves maximization over the set $Z$ of all $\pm 1$-vectors of length $n$ (whose cardinality is $2^{n}$ ):

Proposition 1 For each $A \in R^{m \times n}$ we have

$$
\begin{equation*}
\|A\|_{\infty, 1}=\max _{z \in Z}\|A z\|_{1} \tag{1}
\end{equation*}
$$

where

$$
Z=\left\{z \in R^{n} ; z_{j} \in\{-1,1\} \text { for each } j\right\} .
$$

Moreover, if $A$ is symmetric positive semidefinite, then

$$
\begin{equation*}
\|A\|_{\infty, 1}=\max _{z \in Z} z^{T} A z \tag{2}
\end{equation*}
$$

Proof. 1) If $\|x\|_{\infty}=1$, then $x$ belongs to the unit cube $\{x ;-e \leq x \leq e\}, e=$ $(1, \ldots, 1)^{T}$, which is a convex polyhedron, therefore $x$ can be expressed as a convex combination of its vertices which are exactly the points in $Z$ :

$$
\begin{equation*}
x=\sum_{z \in Z} \lambda_{z} z \tag{3}
\end{equation*}
$$

where $\lambda_{z} \geq 0$ for each $z \in Z$ and $\sum_{z \in Z} \lambda_{z}=1$. From (3) we have

$$
\|A x\|_{1}=\left\|\sum_{z \in Z} \lambda_{z} A z\right\|_{1} \leq \max _{z \in Z}\|A z\|_{1}
$$

hence

$$
\max _{\|x\|_{\infty}=1}\|A x\|_{1} \leq \max _{z \in Z}\|A z\|_{1} \leq \max _{\|x\|_{\infty}=1}\|A x\|_{1}
$$

(since $\|z\|_{\infty}=1$ for each $z \in Z$ ), and (1) follows.
2) Let $A$ be symmetric positive semidefinite and let $z \in Z$. Define $y \in Z$ by $y_{j}=1$ if $(A z)_{j} \geq 0$ and $y_{j}=-1$ if $(A z)_{j}<0(j=1, \ldots, n)$, then

$$
\|A z\|_{1}=y^{T} A z .
$$

Since $A$ is symmetric positive semidefinite, we have

$$
(y-z)^{T} A(y-z) \geq 0,
$$

which implies

$$
2 y^{T} A z \leq y^{T} A y+z^{T} A z \leq 2 \max _{z \in Z} z^{T} A z,
$$

hence

$$
\|A z\|_{1}=y^{T} A z \leq \max _{z \in Z} z^{T} A z
$$

and

$$
\begin{equation*}
\|A\|_{\infty, 1}=\max _{z \in Z}\|A z\|_{1} \leq \max _{z \in Z} z^{T} A z \tag{4}
\end{equation*}
$$

Conversely, for each $z \in Z$ we have

$$
z^{T} A z \leq\left|z^{T} A z\right| \leq|z|^{T}|A z|=e^{T}|A z|=\|A z\|_{1} \leq \max _{z \in Z}\|A z\|_{1}=\|A\|_{\infty, 1},
$$

hence

$$
\max _{z \in Z} z^{T} A z \leq\|A\|_{\infty, 1}
$$

which together with (4) gives (2).
A weaker form of $(2)\left(\|A\|_{\infty, 1}=\max _{\|x\|_{\infty}=1} x^{T} A x\right)$ was given by Tao [8]. In section 4 we shall prove that computing $\|A\|_{\infty, 1}$ is NP-hard. This suggests that unless $\mathrm{P}=\mathrm{NP}$, the formulae (1), (2) cannot be essentially simplified.

## 3 MC-matrices

In order to prove the NP-hardness for a suitably narrow class of matrices, we introduce the following concept (first formulated in [7]):

Definition $1 A$ symmetric $n \times n$ matrix $A=\left(a_{i j}\right)$ is called an MC-matrix ${ }^{1}$ if it is of the form

$$
a_{i j} \begin{cases}=n & \text { if } i=j, \\ \in\{0,-1\} & \text { if } i \neq j\end{cases}
$$

$(i, j=1, \ldots, n)$.
Since an $M C$-matrix is symmetric by definition, there are altogether $2^{n(n-1) / 2} M C$ matrices of size $n$. The basic properties of $M C$-matrices are summed up in the following proposition (where we denote, as customary, by $\|A\|_{1}$ the norm $\|A\|_{1,1}$ described in Section 1):

[^1]Proposition 2 An MC-matrix $A \in R^{n \times n}$ is symmetric positive definite, nonnegative invertible and satisfies

$$
\begin{gather*}
\|A\|_{\infty, 1}=\max _{z \in Z} z^{T} A z,  \tag{5}\\
n \leq\|A\|_{\infty, 1} \leq n(2 n-1) \tag{6}
\end{gather*}
$$

and

$$
\left\|A^{-1}\right\|_{1} \leq 1
$$

Proof. $A$ is symmetric by definition; it is positive definite since for $x \neq 0$,

$$
x^{T} A x \geq n\|x\|_{2}^{2}-\sum_{i \neq j}\left|x_{i} x_{j}\right|=(n+1)\|x\|_{2}^{2}-\|x\|_{1}^{2} \geq\|x\|_{2}^{2}>0
$$

( $\|x\|_{1} \leq \sqrt{n}\|x\|_{2}$ by the Cauchy-Schwarz inequality [4]). Hence (5) holds by Proposition 1. Since $\left|a_{i j}\right| \leq 1$ for $i \neq j$, for each $z \in Z$ and each $i \in\{1, \ldots, n\}$ we have

$$
z_{i}(A z)_{i}=n+\sum_{j \neq i} a_{i j} z_{i} z_{j} \in[1,2 n-1],
$$

hence

$$
n \leq z^{T} A z \leq n(2 n-1)
$$

for each $z \in Z$, and (5) implies (6). Putting

$$
A_{0}=n I-A,
$$

we have that $A_{0} \geq 0, A=n I-A_{0}=n\left(I-\frac{1}{n} A_{0}\right)$ and $\left\|\frac{1}{n} A_{0}\right\|_{1} \leq \frac{n-1}{n}<1$, hence

$$
A^{-1}=\frac{1}{n} \sum_{0}^{\infty}\left(\frac{1}{n} A_{0}\right)^{j} \geq 0
$$

and

$$
\left\|A^{-1}\right\|_{1} \leq \frac{1}{n-\left\|A_{0}\right\|_{1}} \leq 1
$$

which completes the proof.
Hence an $M C$-matrix $A \in R^{n \times n}$ satisfies

$$
\|A\|_{1} \cdot\left\|A^{-1}\right\|_{1}<2 n
$$

i.e., it is well conditioned.

## 4 Computing $\|A\|_{\infty, 1}$ is NP-hard

The following basic result is due to Poljak and Rohn [5] (given there in another formulation without using the concept of an $M C$-matrix).

Theorem 3 The following decision problem is NP-complete:
Instance. An MC-matrix $A$ and a positive integer $\ell$.
Question. Is $z^{T} A z \geq \ell$ for some $z \in Z$ ?
Proof. Let $(N, E)$ be an undirected graph with $N=\{1, \ldots, n\}$. Let $A=\left(a_{i j}\right)$ be given by $a_{i j}=n$ if $i=j, a_{i j}=-1$ if $i \neq j$ and the nodes $i, j$ are connected by an edge, and $a_{i j}=0$ if $i \neq j$ and $i, j$ are not connected. Then $A$ is an $M C$-matrix. For $S \subseteq N$, define the cut $c(S)$ as the number of edges in $E$ whose one endpoint belongs to $S$ and the other one to $N-S$. We shall prove that

$$
\begin{equation*}
\|A\|_{\infty, 1}=4 \max _{S \subseteq N} c(S)-2|E|+n^{2} \tag{7}
\end{equation*}
$$

holds, where $|E|$ denotes the cardinality of $E$. Given a $S \subseteq N$, define a $z \in Z$ by

$$
z_{i}=\left\{\begin{aligned}
1 & \text { if } i \in S, \\
-1 & \text { if } i \notin S
\end{aligned}\right.
$$

Then we have

$$
\begin{aligned}
z^{T} A z & =\sum_{i, j} a_{i j} z_{i} z_{j}=\sum_{i \neq j} a_{i j} z_{i} z_{j}+n^{2} \\
& =\sum_{i \neq j}\left[-\frac{1}{2} a_{i j}\left(z_{i}-z_{j}\right)^{2}+a_{i j}\right]+n^{2} \\
& =-\frac{1}{2} \sum_{z_{i} z_{j}=-1} a_{i j}\left(z_{i}-z_{j}\right)^{2}+\sum_{i \neq j} a_{i j}+n^{2} \\
& =-\frac{1}{2} \sum_{z_{i} z_{j}=-1} 4 a_{i j}+\sum_{i \neq j} a_{i j}+n^{2},
\end{aligned}
$$

hence

$$
\begin{equation*}
z^{T} A z=4 c(S)-2|E|+n^{2} . \tag{8}
\end{equation*}
$$

Conversely, given $z \in Z$, then for $S=\left\{i \in N ; z_{i}=1\right\}$ the same reasoning implies (8). Taking maximum on both sides of (8), we obtain (7) in view of (5).

Hence, given a positive integer $L$, we have that

$$
\begin{equation*}
c(S) \geq L \tag{9}
\end{equation*}
$$

is valid for some $S \subseteq N$ if and only if

$$
z^{T} A z \geq 4 L-2|E|+n^{2}
$$

holds for some $z \in Z$. Since the decision problem (9) is NP-complete ("simple max-cut problem", Garey, Johnson and Stockmeyer [3]), we obtain that the decision problem

$$
\begin{equation*}
z^{T} A z \geq \ell \tag{10}
\end{equation*}
$$

( $\ell$ positive integer) is NP-hard. It is NP-complete since for a guessed solution $z \in Z$ the validity of (10) can be checked in polynomial time.

In this way, in view of (5) we have also proved the following result:
Theorem 4 Computing $\|A\|_{\infty, 1}$ is NP-hard in the class of MC-matrices.
To facilitate formulations of some applications of these results [6], it is advantageous to remove the integer parameter $\ell$ from the formulation of Theorem 3. This can be done by using $M$-matrices instead of $M C$-matrices. Let us recall that $A=\left(a_{i j}\right)$ is called an $M$-matrix if $a_{i j} \leq 0$ for $i \neq j$ and $A^{-1} \geq 0$ (a number of equivalent formulations can be found in Berman and Plemmons [1]); hence each $M C$-matrix is an $M$-matrix (Proposition 2). Since a symmetric $M$-matrix is positive definite [1], this property is not explicitly mentioned in the following theorem:

Theorem 5 The following decision problem is NP-hard:
Instance. A symmetric rational $M$-matrix $A$.
Question. Is $\|A\|_{\infty, 1} \geq 1$ ?
Proof. Given an $M C$-matrix $A$ and a positive integer $\ell$, the assertion

$$
z^{T} A z \geq \ell \text { for some } z \in Z
$$

is equivalent to $\|A\|_{\infty, 1} \geq \ell$ and thereby also to

$$
\left\|\frac{1}{\ell} A\right\|_{\infty, 1} \geq 1
$$

where $\frac{1}{\ell} A$ is a symmetric rational $M$-matrix. Hence the decision problem of Theorem 3 can be reduced in polynomial time to the current one, which is then NP-hard.

Finally we shall show that even computing a sufficiently close approximation of $\|A\|_{\infty, 1}$ is NP-hard:

Theorem 6 Suppose there exists a polynomial-time algorithm which for each MCmatrix $A$ computes a rational number $\nu(A)$ satisfying

$$
\left|\frac{\nu(A)-\|A\|_{\infty, 1}}{\|A\|_{\infty, 1}}\right| \leq \frac{1}{4 n^{2}},
$$

where $n$ is the size of $A$. Then $P=N P$.

Proof. If such an algorithm exists, then

$$
\left|\nu(A)-\|A\|_{\infty, 1}\right| \leq \frac{\|A\|_{\infty, 1}}{4 n^{2}} \leq \frac{n(2 n-1)}{4 n^{2}}<\frac{1}{2}
$$

due to (6), which implies

$$
\|A\|_{\infty, 1}<\nu(A)+\frac{1}{2}<\|A\|_{\infty, 1}+1
$$

and thereby also

$$
\|A\|_{\infty, 1}=\left\lfloor\nu(A)+\frac{1}{2}\right\rfloor
$$

(since $\|A\|_{\infty, 1}$ is integer for an $M C$-matrix $A$ by (5)). Hence the NP-hard problem of Theorem 4 can be solved in polynomial time, implying $\mathrm{P}=\mathrm{NP}$.

Various applications of Theorem 5 for problems with inexact data (regularity, positive definiteness, stability, solvability of linear equations and inequalities, linear and quadratic programming) are given in [6].

## 5 Concluding remarks

We have proved that existence of a polynomial-time algorithm for computing $\|A\|_{\infty, 1}$ with relative accuracy less than $\frac{1}{4 n^{2}}$ implies that the complexity classes P and NP are equal. This runs against the famous unproved conjecture that $\mathrm{P} \neq \mathrm{NP}$ holds, which is widely believed to be true (see Garey and Johnson [2] for details). Hence, the existence of such a polynomial-time algorithm seems highly unlikely, although it cannot be ruled out by current results in complexity theory.

## Acknowledgment

This work was supported by the Charles University Grant Agency under grant 195/96 and by the Czech Republic Grant Agency under grant 201/98/0222.

## References

[1] A. Berman and R. J. Plemmons. Nonnegative Matrices in the Mathematical Sciences. SIAM, Philadelphia, 1994.
[2] M. R. Garey and D. S. Johnson. Computers and Intractability: A Guide to the Theory of NP-Completeness. Freeman, San Francisco, 1979.
[3] M. R. Garey, D. S. Johnson and L. Stockmeyer. Some simplified NP-complete graph problems. Theoretical Computer Science, 1:237-267, 1976.
[4] G. H. Golub and C. F. van Loan. Matrix Computations. The Johns Hopkins University Press, Baltimore, 1996.
[5] S. Poljak and J. Rohn. Checking robust nonsingularity is NP-hard. Mathematics of Control, Signals, and Systems, 6:1-9, 1993.
[6] J. Rohn. Complexity of some linear problems with interval data. Reliable Computing, 3:315-323, 1997.
[7] J. Rohn. Checking positive definiteness or stability of symmetric interval matrices is NP-hard. Commentationes Mathematicae Universitatis Carolinae, 35:795-797, 1994.
[8] P. D. Tao. Algorithmes de calcul du maximum des formes quadratiques sur la boule unité de la norme du maximum. Numerische Mathematik, 45:377-401, 1984.


[^0]:    *Faculty of Mathematics and Physics, Charles University, Prague, Czech Republic, and Institute of Computer Science, Academy of Sciences, Prague, Czech Republic (rohn@uivt.cas.cz).

[^1]:    ${ }^{1}$ from "maximum cut"; see the proof of Theorem 3 below

