

Neural Architecture Search: Mapping the field via network text analysis and my journey through the field

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Outline

Introduction

- ▶ Neural Architecture Search (NAS)

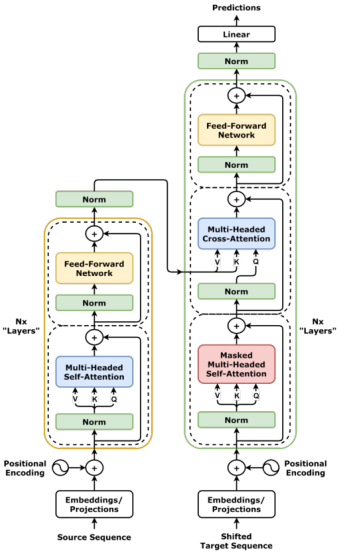
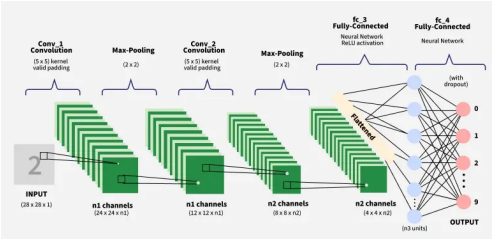
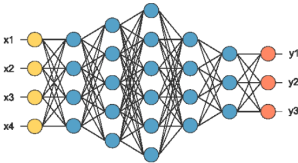
Overview of the field

- ▶ Network text analysis applied to NAS papers

My results in the NAS field

- ▶ Evolutionary NAS approaches and Bayesian optimisation
- ▶ Performance Prediction

(Deep) Neural Networks

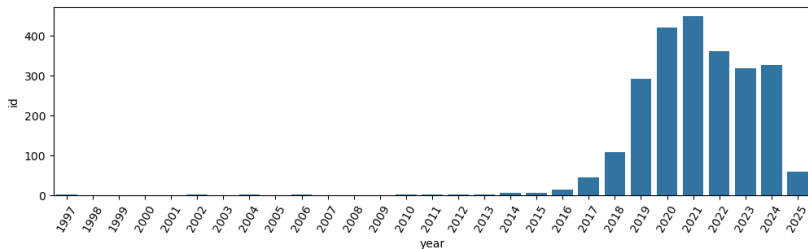


Neural Architecture Search

Neural Architecture Search (NAS)

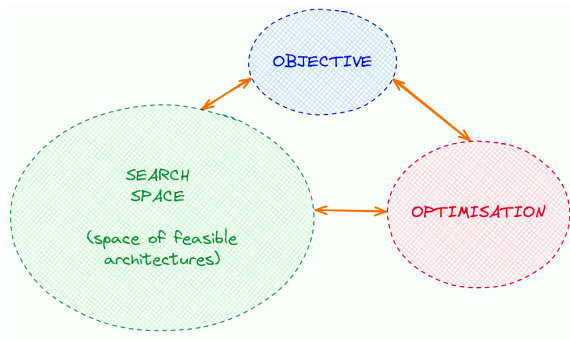
Automating the design of neural network architecture. Given a problem, NAS looks for an optimal architecture.

Research in NAS



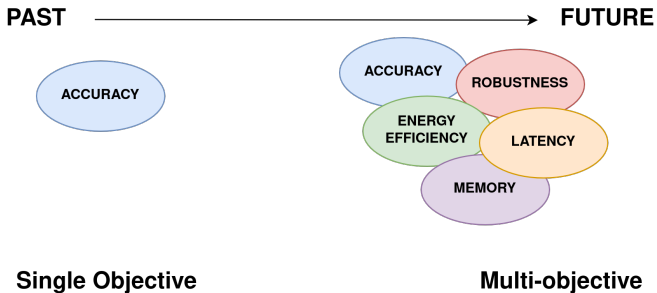
NAS – Optimisation Problem

- ▶ Minimize given objectives over the given search space



Objectives

- Measure the quality of a solution



Text Analysis

Dataset

- ▶ 10000 papers downloaded with the search query `Neural Architecture Search`, filtered using LLM
- ▶ 2 423 papers on NAS from ArXiv

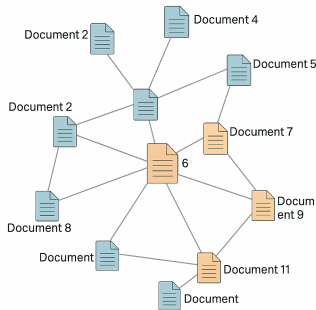
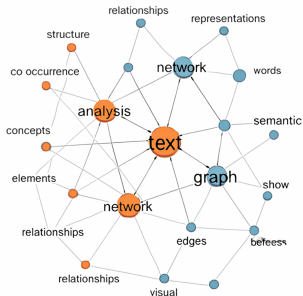
Keywords

- ▶ Fixed set of keywords - documents classified based on abstract using LLM: `reinforcement learning, evolutionary algorithms, bayesian optimisation, multi-objective optimisation, supernet, weight sharing, differentiable optimisation, zero cost proxies or training free, hardware aware search, surrogate models`
- ▶ LLM asked to generate 5 keywords given an paper abstract

Network Text Analysis

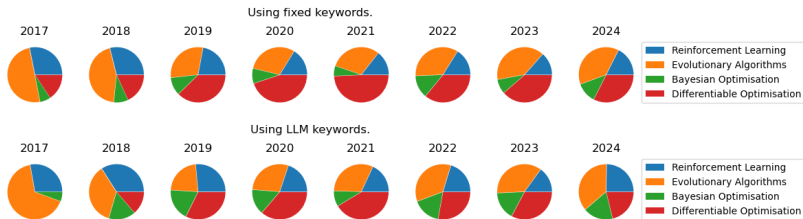
Networks

- ▶ Graphs (nodes, edges)
- ▶ Nodes documents, edges relationships
 - ▶ Citation networks, networks based on shared concepts, keywords
- ▶ Nodes keywords, edges shared documents

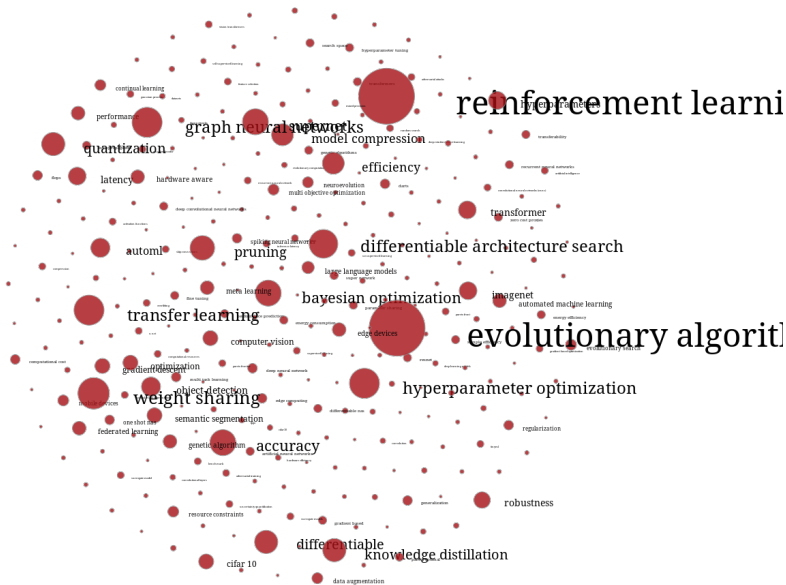


Optimisation

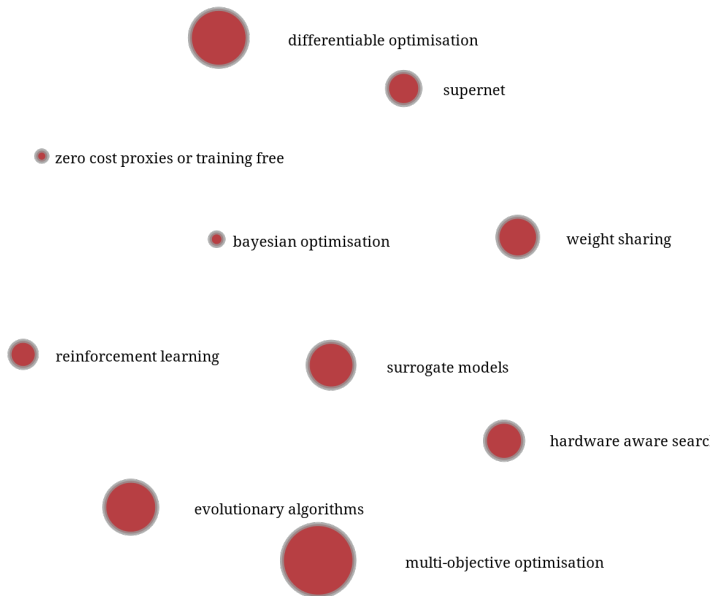
- ▶ Random search (baseline)
- ▶ Evolutionary and genetic algorithms
- ▶ Bayesian optimisation
- ▶ Reinforcement learning
- ▶ Differentiable techniques



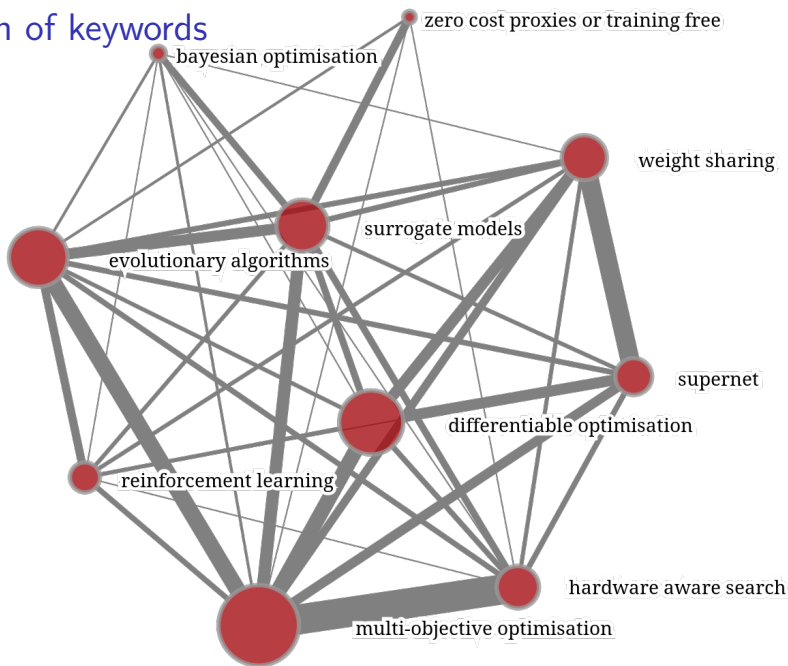
NAS Keywords by LLM



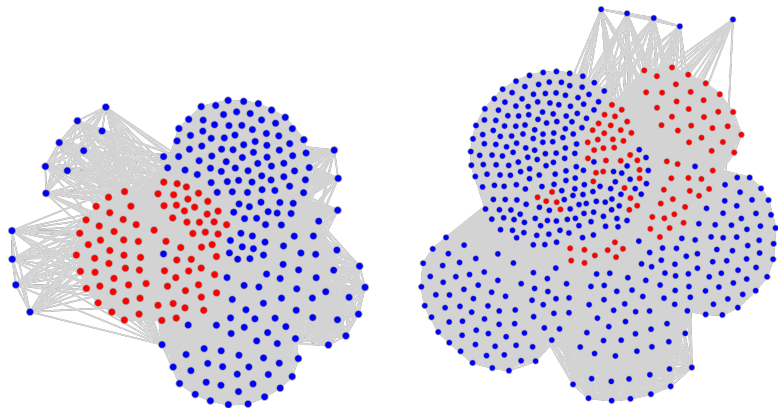
Fixed Selection of Keywords



Graph of keywords



Paper Graph

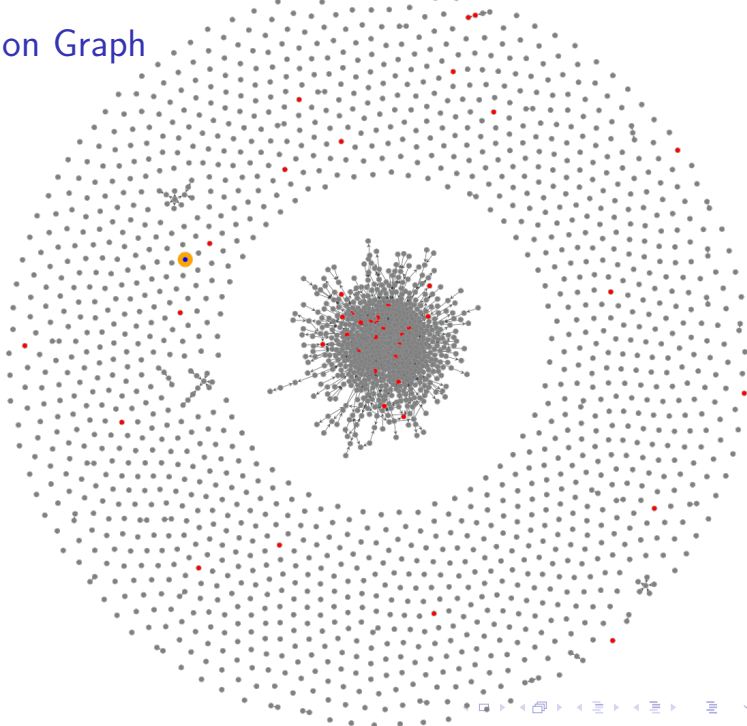


(left) Evolutionary papers

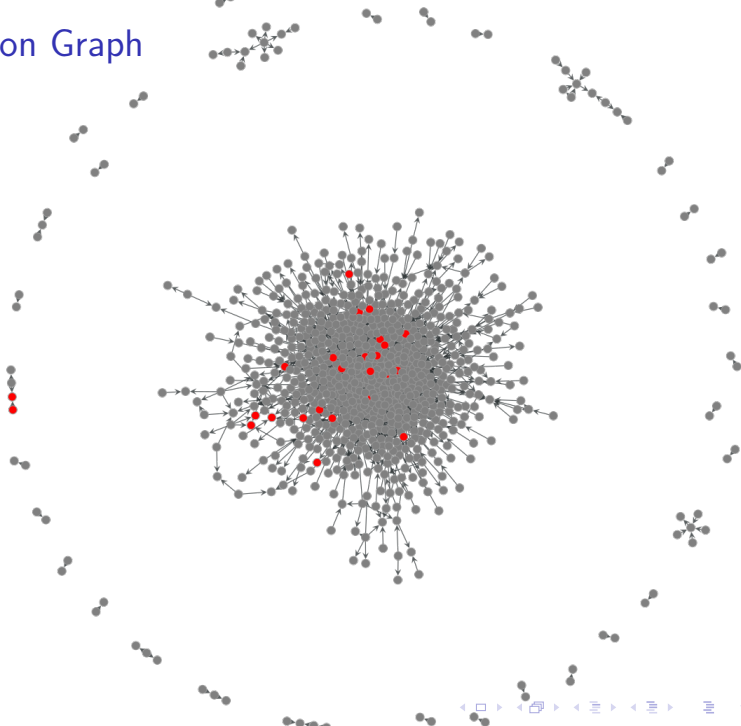
(right) Multi-objective optimisation papers

(red) Surrogate modelling papers (19% of EA, 15% Multi Obj.)

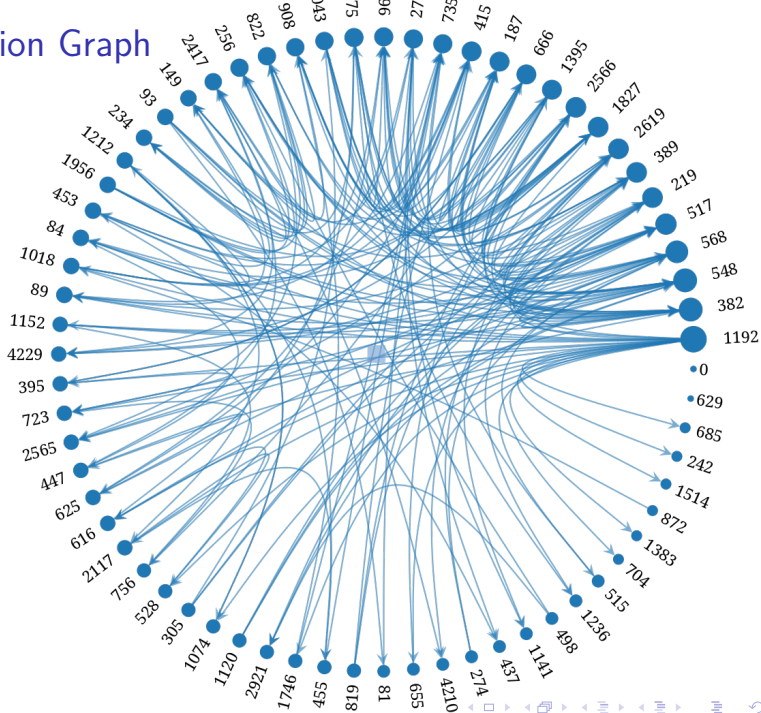
Citation Graph



Citation Graph



Citation Graph

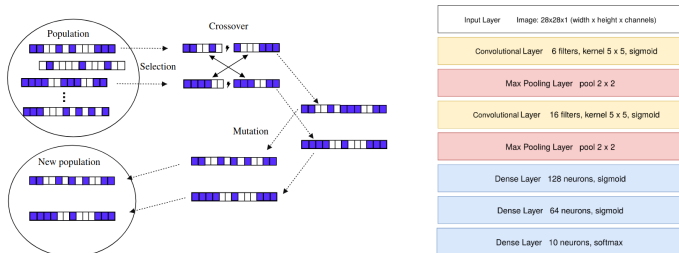


Our Work



Generated by AI.

Evolution of Deep Neural Networks



- ▶ Tested on tabular data (air pollution data set)
- ▶ Image datasets (MNIST, fashion-MNIST)
- ▶ Outperformed fixed networks and SVR

📖 P. Vidnerová, R. Neruda, *Evolving Keras Architectures for Sensor Data Analysis*, FedCSIS 2017

📖 P. Vidnerová, R. Neruda, *Evolution Strategies for Deep Neural Network Models Design*, ITAT 2017 🏆

Asynchronous Evolution

Parallelisation

- ▶ Parallel computation
- ▶ Individuals evaluated one by one
- ▶ No notion of generation
- ▶ As soon as there is an idle processor, new individual is created
- ▶ An arbitrary number of processors
- ▶ Slightly prefers smaller networks

 P. Vidnerová, R. Neruda, *Asynchronous Evolution of Convolutional Networks*, ITAT 2018

Challenges

- ▶ We still need penalise large networks → multi-objective design

Multi-objective approaches

Towards small networks

- ▶ Multi-objective evolution, NSGAI
- ▶ Found more compact networks with comparable accuracy

 P. Vidnerová, Š. Procházka, R. Neruda, *Multiobjective Evolution for Convolutional Neural Network Architecture Search*, ICAISC 2020

 P. Vidnerová, R. Neruda, *Multi-objective Evolution for Deep Neural Network Architecture Search*, ICONIP 2020

Robustness

- ▶ Robustness against outliers, noise, adversarial examples

📖 P. Vidnerová, R. Neruda, *Vulnerability of classifiers to evolutionary generated adversarial examples*, Neural Networks 2020

 J. Kalina, A. Neoral, P. Vidnerová, *Effective Automatic Method Selection for Nonlinear Regression Modeling*, IJNS 2021

Towards Performance Prediction

NAS Computational Cost

- ▶ Evaluation of most objectives requires network training
- ▶ Each candidate network needs to be evaluated

Solutions

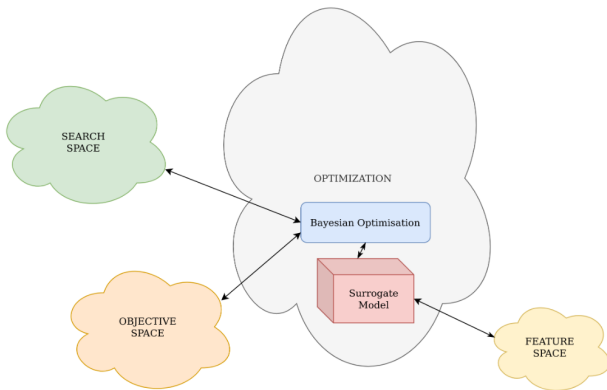
- ▶ Parallelisation - reduces time, but not cost
- ▶ Surrogate models, performance prediction

Performance prediction

- ▶ Imprecise prediction is enough (coarse to grain)
- ▶ Ranking is enough (who is the best)

Bayesian Optimisation

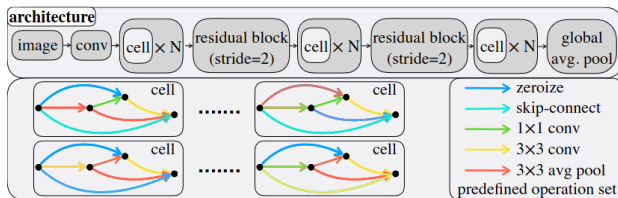
📖 P. Vidnerová, J. Kalina, *Multi-objective Bayesian Optimization for Neural Architecture Search*, ICAISC 2022



Benchmarks and datasets

NAS Benchmarks

- ▶ Datasets of precomputed objectives on selected tasks
- ▶ NAS-Bench-101/201/301, NAS-Bench-201, NAS-Bench-301
- ▶ HW-NAS-Bench, TransNAS-Bench-101, robustness NB201



Source: NAS-Bench-201: Extending the scope of reproducible NAS. ICLR 2020.

Datasets

- ▶ CIFAR 10, 100, 10/100 classes, 60k images, 32x32 pixels
- ▶ ImageNet-16-120 (a downsampled variant, 1000 classes)

Methodology

Regression

- ▶ Random forest regressor
- ▶ Predict accuracy or other metrics

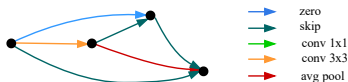
Input data – network encodings

- ▶ Zero cost proxies
- ▶ One hot encoding (of chosen operations)
- ▶ Graph properties

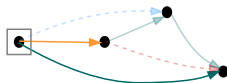
Experiments

- ▶ Analyze predictions
- ▶ Compare different network encodings, predictors

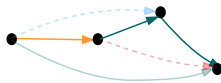
Properties of the neural graph



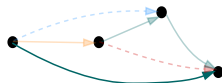
- ▶ We look at properties of the network graph – paths, counts, ...
- ▶ Node degree (c3x3, skip) means input degree counting only conv3x3 and skip
- ▶ Similarly, max path computes the maximum path over allowed operations



Node degree
(c3x3, skip): 2



Max path
(c3x3, skip): 3



Max path
(skip): 1

Properties of the neural graph

- ▶ Number of operations
- ▶ Min path from input over operations O
- ▶ Max path from input to over operations O
- ▶ Out degree of the input node counting only operations O
- ▶ In degree of the output node counting only operations O
- ▶ Mean in/out degree of intermediate nodes counting only operations O

Advantages

- ▶ Simple, interpretable, fast to compute

Disadvantages

- ▶ Highly correlated, dependent on search space

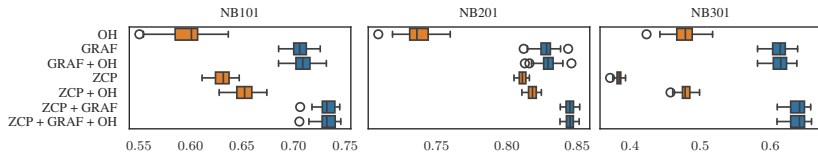
Accuracy prediction

Usage in performance prediction

- ▶ Gathering all properties, we use them as input data to a random forest regressor
- ▶ We compare with other network encodings – all ZCP, one-hot encoding (OH), and their combinations

Results

- ▶ Our results (GRAF) are better than ZCP and OH
- ▶ ZCP combined with network properties is the best

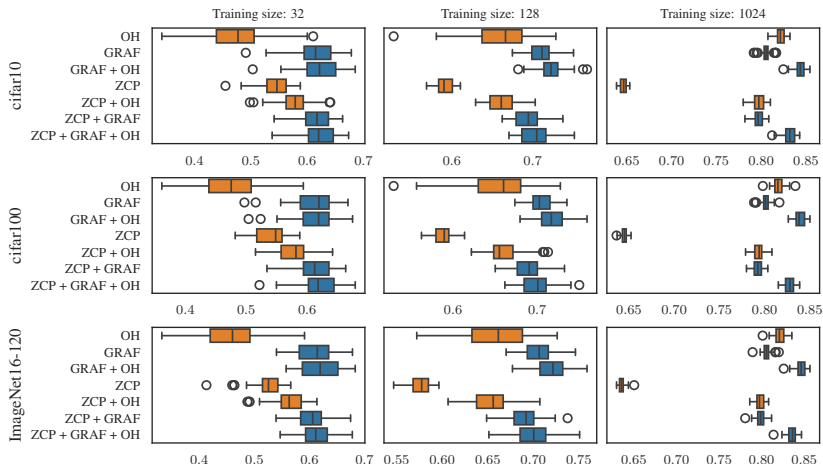


Interpretable prediction

- ▶ For network properties and ZCP, we compute Shapley coefficients (considers feature set importance)
- ▶ We look at the most important features
- ▶ Results – different features are important for diverse tasks
- ▶ nwot is important for CIFAR10, but not for autoencoder
- ▶ autoencoder needs skip connections – result from related work!

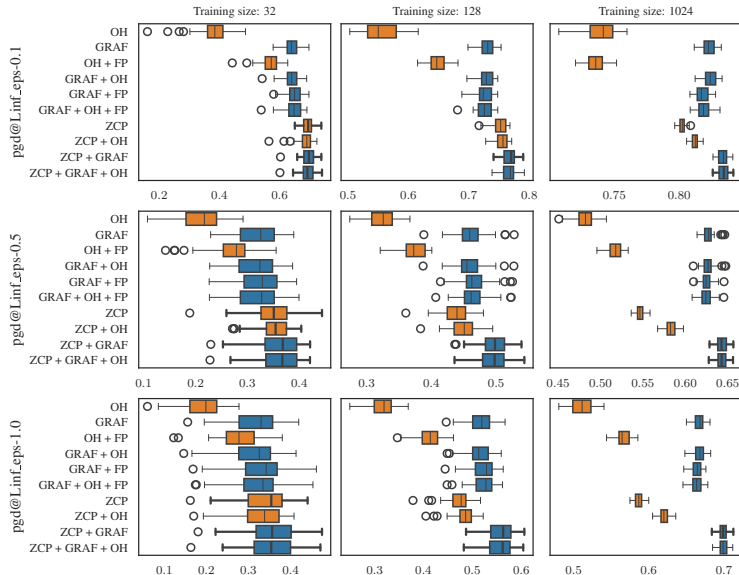
NB201 - cifar-10		TNB101-micro - autoencoder	
Feature name	Mean rank	Feature name	Mean rank
jacov	0.00	min path over skip	0.00
nwot	1.12	jacov	1.00
flops	3.62	fisher	2.00
synflow	4.08	min path over [skip,C3x3]	5.50
min path over [skip,C3x3,C1x1]	4.78	snip	5.58
params	5.04	min path over [skip,C1x1]	5.64
epe_nas	6.04	grad_norm	6.64
zen	6.36	zen	8.08
min path over [skip,C3x3]	11.08	grasp	9.34
min path over skip	11.88	l2_norm	9.74

HW metrics prediction



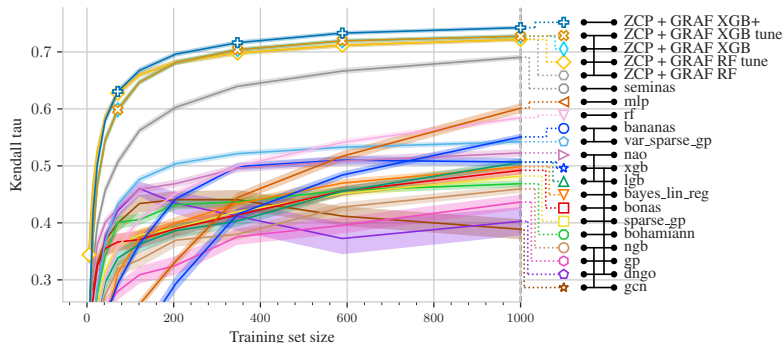
- ▶ HW metrics differ in difficulty of prediction
- ▶ edggpu energy is one of difficult tasks

Robustness prediction



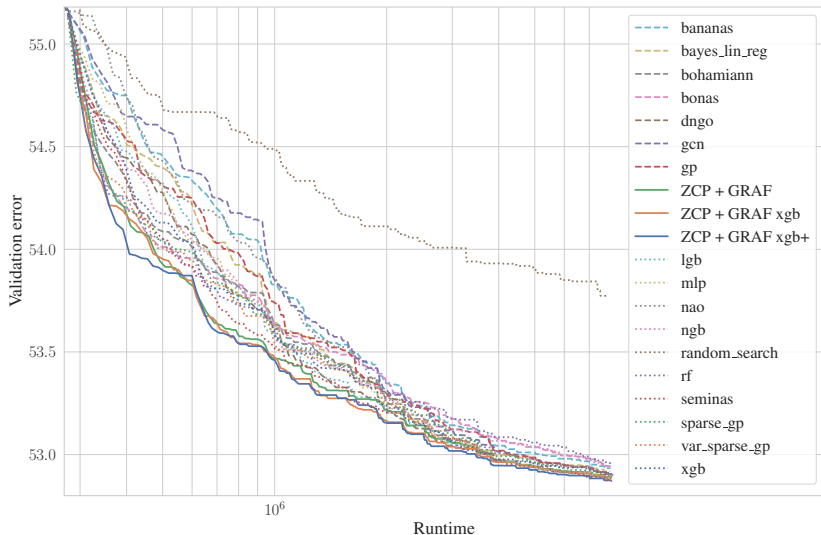
Comparison with existing predictors – NB101, CIFAR10

- ▶ Same experiment as in a predictor survey [1]
- ▶ Outperforms all available predictors
- ▶ Some predictors take much longer to train, e.g. graph neural networks!



[1] Colin White, Arber Zela, Binxin Ru, Yang Liu, & Frank Hutter (2021). How Powerful are Performance Predictors in Neural Architecture Search?. In Advances in Neural Information Processing Systems.

Usage in the NAS process – ImageNet16-120 search



Discussion and future work of GRAF

Pros

- ▶ Better and faster than most predictors
- ▶ Great interpretability
- ▶ Works across tasks and search spaces
- ▶ Baseline for complex predictors

Cons

- ▶ Properties need to be used with ZCP for best performance
- ▶ Some graph neural networks with ZCP can be better

Thank you! Questions?